

# Computer Graphics Through OpenGL: From Theory to Experiments

by Sumanta Guha

*Chapman & Hall/CRC*



# Experimenter Software

(Prepared by Chansophea Chuon and Sumanta Guha)

This file is to help you run the book experiments. It's in pdf format listing all the book experiments, with clickable hyperlinks on top of each. For almost all experiments there is one link, which works in Windows, Mac OS and Linux environments, to bring up the program file, and another to bring up the Windows project, which, of course, works only in a Windows environment. Since source code is not available for the three experiments in the first chapter, the reader is pointed to a folder with Windows and Mac executables.

For experiments asking simply to run a book program, Experimenter brings that program up, while for those asking that a program be modified significantly, the modified program – the modification being made either in the code or comments – comes up. For example, an experiment often asks you to replace a part of a book program with a block of code listed in the text and, possibly, in a file in the `Code/CodeModifications` folder, as well, for easy copy-and-paste. In this case, Experimenter will throw up the modified program either ready to run or needing only a block to be uncommented, saving you the trouble of typing or pasting. For trivial modifications of a program, though, Experimenter links to just the program, leaving you to make changes.

*Note:* The names of the folders in `ExperimenterSource` – e.g., `Experiment-RotateTeapotMore` for Experiment 4.7 of the text – mostly do not appear in the text itself and are of little relevance.

The Experimenter is meant as a convenience. If you are a do-it-yourself type preferring to tinker with the experiment programs on your own, then you don't need it.

*Installing and using Experimenter:* Download the directory `Experimenter-Source` from the book's website [www.sumantaguha.com](http://www.sumantaguha.com) and install it as a subfolder of the same folder where you have `Experimenter.pdf` (the file you are reading, also to be found at the book's site). It's best to use Adobe Reader to open `Experimenter.pdf` as other pdf readers might not be able to resolve the hyperlinks. Windows users should note that Experimenter

will be slow in bringing up each project the first time, as various config files have to be generated locally; it should be fast after that.

If you need to learn how to set up an environment in which to run OpenGL code, see Appendix B of the book, which is also included at the end of this file.

*Adding your own experiments to Experimenter:* Presuming you are using Latex, first include the `hyperref` package in your document. In our case, we did so with the line

```
\usepackage[pdftex]{hyperref}
```

Subsequently, add hyperlinks as follows (a sample from Experimenter's Latex file):

```
Click for \ic{square.cpp}~~~  
\href{run:Experimentersource/Chapter2/Square/square.cpp}  
  {{\color{red}\ic{Program}}}  
\href{run:Experimentersource/Chapter2/Square/Square.vcxproj}  
  {{\color{red}\ic{Windows Project}}}
```

Once you have created your own Experimenter-like document with clickable hyperlinks, you can mix and match pages of it with Experimenter by using a pdf document manipulating tool.

We hope you find Experimenter of help as you read the book. All feedback is welcome: send mail to [sg@sumantaguha.com](mailto:sg@sumantaguha.com).

Part I

**Hello World**



# CHAPTER 1

## An Invitation to Computer Graphics

*Executables for Windows and the Mac are in the folder  
ExperimenterSource/Chapter1/Ellipsoid.*

**Experiment 1.1.** Open the folder `Invitation/Ellipsoid` in the Code directory and, hopefully, you'll then be able to run at least one of the two executables there for the `Ellipsoid` program – one for Windows and one for the Mac. The program draws an ellipsoid (an egg shape). The left of Figure 1.16 shows the initial screen. There's plenty of interactivity to try as well. Press any of the four arrow keys, as well as the page up and down keys, to change the shape of the ellipsoid, and 'x', 'X', 'y', 'Y', 'z' and 'Z' to turn it.

It's a simple object, but the three-dimensionality of it comes across rather nicely does it not? As with almost all surfaces that we'll be drawing ourselves, the ellipsoid is made up of triangles. To see these press the space bar to enter wireframe mode. Pressing space again restores the filled mode. The wireframe reveals the ellipsoid to be made of a mesh of triangles decorated with large points. A color gradient has apparently been applied toward the poles as well.

That's it. There's really not much more to this program: no lighting or blending or other effects you may have heard of as possible using OpenGL (the program was written just a few weeks into the semester). It's just a bunch of colored triangles and points laid out in 3D space. The magic is in those last two words: *3D space*. 3D modeling is all about making things in 3D space – not just on a flat plane – to create an illusion of depth, even when they are viewed on a flat screen. **End**

*Executables for Windows and the Mac are in the folder  
ExperimenterSource/Chapter1/AnimatedGarden.*

**Experiment 1.2.** Our next program is animated. It creates a garden that grows and grows and grows. You will find executables in the folder `Invitation/AnimatedGarden` in the `Code` directory. Press enter to start the animation; enter again to stop it. The delete key restarts the animation, while the period (full stop) key toggles between the camera rotating and not. Again, the space key toggles between wireframe and filled. The middle of Figure 1.16 is a screenshot a few seconds into the animation.

As you can see from the wireframe, there's again a lot of triangles (in fact, the flowers might remind you of the ellipsoid from the previous program). The plant stems are thick lines and, if you look carefully, you'll spot points as well. The one special effect this program has that `Ellipsoid` did not is blending. **End**

*Executables for Windows and the Mac are in the folder  
ExperimenterSource/Chapter1/Dominos.*

**Experiment 1.3.** Our final program is a movie which shows a Rube Goldberg domino effect with “real” dominos. The executables are in the folder `Invitation/Dominos` in the `Code` directory. Simply press enter to start and stop the movie. The screenshot on the right of Figure 1.16 is from part way through.

This program has a bit of everything – textures, lighting, camera movement and, of course, a nicely choreographed animation sequence, among others. **End**

# CHAPTER 2

## On to OpenGL and 3D Computer Graphics

Click for [square.cpp](#) [Program](#) [Windows Project](#)

**Experiment 2.1.** Run `square.cpp`.

*Note:* See Appendix B for how to install OpenGL and run our programs on Windows, Linux and Mac OS platforms.

In the OpenGL window appears a black square over a white background, as shown in Figure 2.1 (where blue stands in for white to distinguish it from the paper). We are going to understand next how the square is drawn, and gain some insight as well into the workings behind the scene. **End**

Click for [square.cpp](#) [Program](#) [Windows Project](#)

**Experiment 2.2.** Change the `glutInitWindowSize()` parameter values of `square.cpp`\* – first to `glutInitWindowSize(300, 300)` and then `glutInitWindowSize(500, 250)`. The square changes in size, and even shape, with the OpenGL window. Therefore, coordinate values appear not to specify any kind of absolute units on the screen. **End**

Click for [square.cpp modified](#) [Program](#) [Windows Project](#)

---

\*When we refer to `square.cpp`, or any `program.cpp`, it's always to the original version in the `Code` directory, so if you've modified the code for an earlier experiment you'll need to copy back the original.

**Experiment 2.3.** Change only the viewing box of `square.cpp` by replacing `glOrtho(0.0, 100.0, 0.0, 100.0, -1.0, 1.0)` with `glOrtho(-100, 100.0, -100.0, 100.0, -1.0, 1.0)`. The location of the square in the new viewing box is different and, so as well, the result of shoot-and-print. Figure 2.10 explains how. **End**

Click for `square.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 2.4.** Change the parameters of `glutInitWindowPosition(x, y)` in `square.cpp` from the current (100, 100) to a few different values to determine the location of the origin (0, 0) of the computer screen, as well as the orientation of the screen's own  $x$ -axis and  $y$ -axis. **End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 2.5.** Add another square by inserting the following right after the code for the original square in `square.cpp` (Block 2):

```
glBegin(GL_POLYGON);
    glVertex3f(120.0, 120.0, 0.0);
    glVertex3f(180.0, 120.0, 0.0);
    glVertex3f(180.0, 180.0, 0.0);
    glVertex3f(120.0, 180.0, 0.0);
glEnd();
```

From the value of its vertex coordinates the second square evidently lies entirely outside the viewing box.

If you run now there's no sign of the second square in the OpenGL window! This is because OpenGL *clips* the scene to within the viewing box before rendering, so that objects or parts of objects drawn outside are not rendered. Clipping is a stage in the graphics pipeline. We'll not worry about its implementation at this time, only the effect it has. **End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 2.6.** For a more dramatic illustration of clipping, first replace the square in the original `square.cpp` with a triangle; in particular, replace the polygon code with the following (Block 3):

```
glBegin(GL_POLYGON);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(80.0, 80.0, 0.0);
glEnd();
```

Next, lift the first vertex up the  $z$ -axis by changing it to `glVertex3f(20.0, 20.0, 0.5)`; lift it further by changing its  $z$ -value to 1.5 (Figure 2.12 is a screenshot), then 2.5 and, finally, 10.0. Make sure you believe that what you see in the last three cases is indeed a triangle clipped to within the viewing box – Figure 2.13 may be helpful. **End**

Click for `square.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 2.7.** The color of the square in `square.cpp` is specified by the three parameters of the `glColor3f(0.0, 0.0, 0.0)` statement in the `drawScene()` routine, each of which gives the value of one of the three primary components, *blue*, *green* and *red*.

Determine which of the three parameters of `glColor3f()` specifies the blue, green and red components by setting in turn each to 1.0 and the others to 0.0. In fact, verify the following table:

Call	Color
<code>glColor3f(0.0, 0.0, 0.0)</code>	Black
<code>glColor3f(1.0, 0.0, 0.0)</code>	Red
<code>glColor3f(0.0, 1.0, 0.0)</code>	Green
<code>glColor3f(0.0, 0.0, 1.0)</code>	Blue
<code>glColor3f(1.0, 1.0, 0.0)</code>	Yellow
<code>glColor3f(1.0, 0.0, 1.0)</code>	Magenta
<code>glColor3f(0.0, 1.0, 1.0)</code>	Cyan
<code>glColor3f(1.0, 1.0, 1.0)</code>	White

**End**

Click for `square.cpp modified` [Program](#) [Windows](#) [Project](#)

**Experiment 2.8.** Add the additional color declaration statement `glColor3f(1.0, 0.0, 0.0)` just after the existing one `glColor3f(0.0, 0.0, 0.0)` in the drawing routine of `square.cpp` so that the foreground color block becomes

```
// Set foreground (or drawing) color.  
glColor3f(0.0, 0.0, 0.0);  
glColor3f(1.0, 0.0, 0.0);
```

The square is drawn red because the *current* value of the foreground color is red when each of its vertices is specified. **End**

Click for `square.cpp modified` [Program](#) [Windows](#) [Project](#)

**Experiment 2.9.** Replace the polygon declaration part of `square.cpp` with the following to draw two squares (Block 5):

```
glColor3f(1.0, 0.0, 0.0);
glBegin(GL_POLYGON);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(80.0, 80.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
glEnd();

glColor3f(0.0, 1.0, 0.0);
glBegin(GL_POLYGON);
    glVertex3f(40.0, 40.0, 0.0);
    glVertex3f(60.0, 40.0, 0.0);
    glVertex3f(60.0, 60.0, 0.0);
    glVertex3f(40.0, 60.0, 0.0);
glEnd();
```

A small green square appears inside a larger red one (Figure 2.14). Obviously, this is because the foreground color is red for the first square, but green for the second. One says that the color red *binds* to the first square – or, more precisely, to each of its four specified vertices – and green to the second square. These bound values specify the color *attribute* of either square. Generally, the values of those state variables which determine how it is rendered collectively form a primitive’s attribute set.

Flip the order in which the two squares appear in the code by cutting the seven statements that specify the red square and pasting them after those to do with the green one. The green square is overwritten by the red one and no longer visible because OpenGL draws in *code order*: primitives are rendered to the screen as they are specified in the code. This is called *immediate mode* graphics. One could also call it *memory-less* graphics, as primitives are not stored in the rendering pipeline, but drawn (and forgotten). **End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 2.10.** Replace the polygon declaration part of `square.cpp` with (Block 6):

```
glBegin(GL_POLYGON);
    glColor3f(1.0, 0.0, 0.0);
    glVertex3f(20.0, 20.0, 0.0);
    glColor3f(0.0, 1.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glColor3f(0.0, 0.0, 1.0);
    glVertex3f(80.0, 80.0, 0.0);
    glColor3f(1.0, 1.0, 0.0);
```

```
    glVertex3f(20.0, 80.0, 0.0);
glEnd();
```

The different color values bound to the four vertices of the square are evidently *interpolated* over the rest of the square as you can see in Figure 2.15. In fact, this is most often the case with OpenGL: numerical attribute values specified at the vertices of a primitive are interpolated throughout its interior. In a later chapter we'll see exactly what it means to interpolate and how OpenGL goes about the task. **End**

[Click for square.cpp modified](#)   [Program](#)   [Windows](#)   [Project](#)

**Experiment 2.11.** Replace `glBegin(GL_POLYGON)` with `glBegin(GL_POINTS)` in `square.cpp` and make the point size bigger with a call to `glPointSize(5.0)`, so that the part drawing the polygon is now

```
glPointSize(5.0); // Set point size.
glBegin(GL_POINTS);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(80.0, 80.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
glEnd();
```

**End**

[Click for square.cpp modified](#)   [Program](#)   [Windows](#)   [Project](#)

**Experiment 2.12.** Continue, replacing `GL_POINTS` with `GL_LINES`, `GL_LINE_STRIP` and, finally, `GL_LINE_LOOP`. **End**

[Click for square.cpp modified](#)   [Program](#)   [Windows](#)   [Project](#)

**Experiment 2.13.** Replace the polygon declaration part of `square.cpp` with (Block 8):

```
glBegin(GL_TRIANGLES);
    glVertex3f(10.0, 90.0, 0.0);
    glVertex3f(10.0, 10.0, 0.0);
    glVertex3f(35.0, 75.0, 0.0);
    glVertex3f(30.0, 20.0, 0.0);
    glVertex3f(90.0, 90.0, 0.0);
    glVertex3f(80.0, 40.0, 0.0);
glEnd();
```

Click for [square.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 2.14.** In fact, it's often easier to decipher a 2D primitive by viewing it in outline. Accordingly, continue the preceding experiment by inserting the call `glPolygonMode(GL_FRONT_AND_BACK, GL_LINE)` in the drawing routine and, further, replacing `GL_TRIANGLES` with `GL_TRIANGLE_STRIP`. The relevant part of the display routine then is as below:

```
// Set polygon mode.
glPolygonMode(GL_FRONT_AND_BACK, GL_LINE);

// Draw a triangle strip.
glBegin(GL_TRIANGLE_STRIP);
    glVertex3f(10.0, 90.0, 0.0);
    glVertex3f(10.0, 10.0, 0.0);
    glVertex3f(35.0, 75.0, 0.0);
    glVertex3f(30.0, 20.0, 0.0);
    glVertex3f(90.0, 90.0, 0.0);
    glVertex3f(80.0, 40.0, 0.0);
glEnd();
```

End

Click for [square.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 2.15.** Replace the polygon declaration part of `square.cpp` with (Block 9):

```
glBegin(GL_TRIANGLE_FAN);
    glVertex3f(10.0, 10.0, 0.0);
    glVertex3f(15.0, 90.0, 0.0);
    glVertex3f(55.0, 75.0, 0.0);
    glVertex3f(80.0, 30.0, 0.0);
    glVertex3f(90.0, 10.0, 0.0);
glEnd();
```

Apply both the filled and outlined drawing modes.

End

Click for [square.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 2.16.** Replace the polygon declaration part of `square.cpp` with (Block 10):

```

glBegin(GL_QUADS);
    glVertex3f(10.0, 90.0, 0.0);
    glVertex3f(10.0, 10.0, 0.0);
    glVertex3f(40.0, 20.0, 0.0);
    glVertex3f(35.0, 75.0, 0.0);
    glVertex3f(15.0, 80.0, 0.0);
    glVertex3f(20.0, 10.0, 0.0);
    glVertex3f(90.0, 20.0, 0.0);
    glVertex3f(90.0, 75.0, 0.0);
glEnd();

```

Apply both the filled and outlined drawing modes.

**End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 2.17.** Replace the polygon declaration part of `square.cpp` with (Block 11):

```

glBegin(GL_QUAD_STRIP);
    glVertex3f(10.0, 90.0, 0.0);
    glVertex3f(10.0, 10.0, 0.0);
    glVertex3f(30.0, 80.0, 0.0);
    glVertex3f(40.0, 15.0, 0.0);
    glVertex3f(60.0, 75.0, 0.0);
    glVertex3f(60.0, 25.0, 0.0);
    glVertex3f(90.0, 90.0, 0.0);
    glVertex3f(85.0, 20.0, 0.0);
glEnd();

```

Apply both the filled and outlined drawing modes.

**End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 2.18.** Replace the polygon declaration of `square.cpp` with (Block 12):

```

glBegin(GL_POLYGON);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(50.0, 20.0, 0.0);
    glVertex3f(80.0, 50.0, 0.0);
    glVertex3f(80.0, 80.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
glEnd();

```

You see a convex 5-sided polygon (Figure 2.19(a)).

**End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 2.19.** Replace the polygon declaration of `square.cpp` with (Block 13):

```
glBegin(GL_POLYGON);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(40.0, 40.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
glEnd();
```

Display it *both* filled and outlined using appropriate `glPolygonMode()` calls. A non-convex quadrilateral is drawn in either case (Figure 2.19(b)). Next, keeping the *same* cycle of vertices as above, list them starting with `glVertex3f(80.0, 20.0, 0.0)` instead (Block 14):

```
glBegin(GL_POLYGON);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(40.0, 40.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
    glVertex3f(20.0, 20.0, 0.0);
glEnd();
```

Make sure to display it both filled and outlined. When filled it's a triangle, while outlined it's a non-convex quadrilateral identical to the one output earlier (Figure 2.19(c))! Because the cyclic order of the vertices is unchanged, shouldn't it be as in Figure 2.19(b) both filled and outlined? **End**

[Click for circle.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 2.20.** Run `circle.cpp`. Increase the number of vertices in the line loop

```
glBegin(GL_LINE_LOOP);
    for(i = 0; i < numVertices; ++i)
    {
        glColor3ub(rand()%256, rand()%256, rand()%256);
        glVertex3f(X + R * cos(t), Y + R * sin(t), 0.0);
        t += 2 * PI / numVertices;
    }
glEnd();
```

by pressing '+' till it "becomes" a circle, as in the screenshot of Figure 2.21. Press '-' to decrease the number of vertices. The `glColor3ub()` statement is for eye candy. **End**

**Experiment 2.21.** Run `parabola.cpp`. Press ‘+/-’ to increase/decrease the number of vertices of the approximating line strip. Figure 2.23 is a screenshot with enough vertices to make a smooth-looking parabola.

The vertices are equally spaced along the  $x$ -direction. The parametric equations implemented are

$$x = 50 + 50t, y = 100t^2, z = 0, \quad -1 \leq t \leq 1$$

the constants being chosen so that the parabola is centered in the OpenGL window. **End**

Click for `circularAnnuluses.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 2.22.** Run `circularAnnuluses.cpp`. Three identical-looking red circular annuluses (see Figure 2.24) are drawn in three *different* ways:

- i) Upper-left: There is not a real hole. The white disc *overwrites* the red disc as it appears later in the code.

```
glColor3f(1.0, 0.0, 0.0);
drawDisc(20.0, 25.0, 75.0, 0.0);
glColor3f(1.0, 1.0, 1.0);
drawDisc(10.0, 25.0, 75.0, 0.0);
```

*Note:* The first parameter of `drawDisc()` is the radius and the remaining three the coordinates of the center.

- ii) Upper-right: There is not a real hole either. A white disc is *drawn closer* to the viewer than the red disc thus blocking it out.

```
glEnable(GL_DEPTH_TEST);
glColor3f(1.0, 0.0, 0.0);
drawDisc(20.0, 75.0, 75.0, 0.0);
glColor3f(1.0, 1.0, 1.0);
drawDisc(10.0, 75.0, 75.0, 0.5);
glDisable(GL_DEPTH_TEST);
```

Observe that the  $z$ -value of the white disc’s center is greater than the red disc’s. We’ll discuss the mechanics of one primitive blocking out another momentarily.

- iii) Lower: A true circular annulus with a real hole.

```
if (isWire) glPolygonMode(GL_FRONT, GL_LINE);
else glPolygonMode(GL_FRONT, GL_FILL);
```

```
glColor3f(1.0, 0.0, 0.0);  
glBegin(GL_TRIANGLE_STRIP);  
...  
glEnd();
```

Press the space bar to see the wireframe of a triangle strip. **End**

Click for [helix.cpp](#) **Program** **Windows** **Project**

**Experiment 2.23.** Okay, run `helix.cpp` now. All we see is a circle as in Figure 2.27(a)! There's no sign of any coiling up or down. The reason, of course, is that the orthographic projection onto the viewing face flattens the helix. Let's see if it makes a difference to turn the helix upright, in particular, so that it coils around the  $y$ -axis. Accordingly, replace the statement

```
glVertex3f(R * cos(t), R * sin(t), t - 60.0);
```

in the drawing routine with

```
glVertex3f(R * cos(t), t, R * sin(t) - 60.0);
```

Hmm, not a lot better (Figure 2.27(b))! **End**

Click for [helix.cpp modified](#) **Program** **Windows** **Project**

**Experiment 2.24.** Fire up the original `helix.cpp` program. Replace orthographic projection with perspective projection; in particular, replace the projection statement

```
glOrtho(-50.0, 50.0, -50.0, 50.0, 0.0, 100.0);
```

with

```
glFrustum(-5.0, 5.0, -5.0, 5.0, 5.0, 100.0);
```

You can see a real spiral now (Figure 2.30(a)). View the upright version as well (Figure 2.30(b)), replacing

```
glVertex3f(R * cos(t), R * sin(t), t - 60.0);
```

with

```
glVertex3f(R * cos(t), t, R * sin(t) - 60.0);
```

A lot better than the orthographic version is it not?! **End**

**Experiment 2.25.** Run `moveSphere.cpp`, which simply draws a movable sphere in the OpenGL window. Press the left, right, up and down arrow keys to move the sphere, the space bar to rotate it and 'r' to reset.

The sphere appears distorted as it nears the periphery of the window, as you can see from the screenshot in Figure 2.31. Can you guess why? Ignore the code, especially unfamiliar commands such as `glTranslatef()` and `glRotatef()`, except for the fact that the projection is perspective.

This kind of *peripheral distortion* of a 3D object is unavoidable in any viewing system which implements the synthetic-camera model. It happens with a real camera as well, but we don't notice it as much because the field of view when snapping pictures is usually quite large and objects of interest tend to be centered. **End**

Click for [hemisphere.cpp](#) **Program** **Windows** **Project**

**Experiment 2.26.** Run `hemisphere.cpp`, which implements exactly the strategy just described. You can verify this from the snippet that draws the hemisphere:

```
for(j = 0; j < q; j++)
{
// One latitudinal triangle strip.
glBegin(GL_TRIANGLE_STRIP);
for(i = 0; i <= p; i++)
{
    glVertex3f(R * cos((float)(j+1)/q * PI/2.0) *
               cos(2.0 * (float)i/p * PI),
              R * sin((float)(j+1)/q * PI/2.0),
              R * cos((float)(j+1)/q * PI/2.0) *
               sin(2.0 * (float)i/p * PI));
    glVertex3f(R * cos((float)j/q * PI/2.0) *
               cos(2.0 * (float)i/p * PI),
              R * sin((float)j/q * PI/2.0),
              R * cos((float)j/q * PI/2.0) *
               sin(2.0 * (float)i/p * PI));
}
glEnd();
}
```

Increase/decrease the number of longitudinal slices by pressing 'P/p'. Increase/decrease the number of latitudinal slices by pressing 'Q/q'. Turn the hemisphere about the axes by pressing 'x', 'X', 'y', 'Y', 'z' and 'Z'. See Figure 2.34 for a screenshot. **End**

Click for [hemisphere.cpp](#) **Program** **Windows** **Project**

**Experiment 2.27.** Playing around a bit with the code will help clarify the construction of the hemisphere:

- (a) Change the range of the hemisphere's outer loop from

```
for(j = 0; j < q; j++)
```

to

```
for(j = 0; j < 1; j++)
```

Only the bottom strip is drawn. The keys 'P/p' and 'Q/q' still work.

- (b) Change it again to

```
for(j = 0; j < 2; j++)
```

Now, the bottom two strips are drawn.

- (c) Reduce the range of both loops:

```
for(j = 0; j < 1; j++)  
...  
    for(i = 0; i <= 1; i++)  
    ...
```

The first two triangles of the bottom strip are drawn.

- (d) Increase the range of the inner loop by 1:

```
for(j = 0; j < 1; j++)  
...  
    for(i = 0; i <= 2; i++)  
    ...
```

The first four triangles of the bottom strip are drawn.

**End**

Part II

**Tricks of the Trade**



# CHAPTER 3

## An OpenGL Toolbox

Click for [squareAnnulus1.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 3.1.** Run `squareAnnulus1.cpp`. A screenshot is seen in Figure 3.1(a). Press the space bar to see the wireframe in Figure 3.1(b).

It is a plain-vanilla program which draws the square annulus diagrammed in Figure 3.2 using a single triangle strip (and multiply-colored vertices).

**End**

Click for [squareAnnulus2.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 3.2.** Run `squareAnnulus2.cpp`.

It draws the same annulus as `squareAnnulus1.cpp`, except that the vertex coordinates and color data are now stored in two-dimensional global arrays, `vertices` and `colors`, respectively. A vector of coordinate values is retrieved by the *pointer form* (also called *vector form*) of vertex declaration, namely, `glVertex3fv(*pointer)`. Similarly, a vector of color values is retrieved with the pointer form `glColor3fv(*pointer)`.

Compared with `squareAnnulus1.cpp`, the obvious efficiency gained is in placing vertex and color data at one place in the code and then simply pointing to them from elsewhere.

**End**

Click for [squareAnnulus3.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 3.3.** Run `squareAnnulus3.cpp`.

It again draws the same colorful annulus as before. The coordinates and color data of the vertices are stored in one-dimensional global vertex arrays, `vertices` and `colors`, respectively, as in `squareAnnulus2.cpp`, except, now,

the arrays are flat and not 2D. The  $i$ th vector of values from both arrays is retrieved *simultaneously* with a single `glArrayElement( $i$ )` call.

Note the initialization steps:

1. Two vertex arrays are enabled with calls to `glEnableClientState( $array$ )`, where  $array$  is, successively, `GL_VERTEX_ARRAY` and `GL_COLOR_ARRAY`. There are other possible values for the parameter  $array$  to store different kinds of data (we'll be storing normal and texture coordinates later).
2. The data for the two vertex arrays is specified with a call to `glVertexPointer( $size$ ,  $type$ ,  $stride$ ,  $*pointer$ )` and a call to `glColorPointer( $size$ ,  $type$ ,  $stride$ ,  $*pointer$ )`. The parameter  $pointer$  is the address of the start of the data array,  $type$  declares the data type,  $size$  is the number of values per vertex (both coordinate and color arrays store 3 values for each vertex) and  $stride$  is the byte offset between the start of the values for successive vertices (0 indicates that values for successive vertices are not separated). End

Click for [squareAnnulus4.cpp](#) Program Windows Project

### Experiment 3.4. Run `squareAnnulus4.cpp`.

The code is even more concise with the application of a single call of the form `glDrawElements( $primitive$ ,  $count$ ,  $type$ ,  $*indices$ )` to draw the triangle strip. Parameter  $primitive$  is a geometric primitive,  $indices$  is the address of the start of an array of indices,  $type$  is the data type of the  $indices$  array and  $count$  is the number indices to use. The call itself is equivalent to the loop

```
glBegin( $primitive$ );  
    for( $i$  = 0;  $i$  <  $count$ ;  $i$ ++) glArrayElement( $indices$ [ $i$ ]);  
glEnd();
```

End

Click for [squareAnnulusAndTriangle.cpp](#) Program Windows Project

**Experiment 3.5.** Run `squareAnnulusAndTriangle.cpp`, which adds a triangle inside the annulus of the `squareAnnulus*.cpp` programs. See Figure 3.3 for a screenshot.

This program demonstrates the use of multiple vertex arrays. The vertex arrays `vertices1` and `colors1` contain the coordinate and color data, respectively, for the annulus, exactly as in `squareAnnulus3.cpp` and `squareAnnulus4.cpp`.

The single vertex array `vertices2AndColors2Intertwined` for the triangle, on the other hand, is *intertwined* in that it contains both coordinate and color data together. When pointing to data for the triangle, the *stride* parameter of both the `glVertexPointer()` and `glColorPointer()` calls is set to 6 times the number of bytes in a `float` data item, as there are 6 such items between the start of successive coordinate or color vectors in the intertwined array. **End**

Click for `helixList.cpp` [Program](#) [Windows Project](#)

**Experiment 3.6.** Run `helixList.cpp`, which shows many copies of the same helix, variously transformed and colored. Figure 3.4 is a screenshot.

Here's the snippet from the initialization routine that makes a display list to draw the helix:

```
aHelix = glGenLists(1);
glNewList(aHelix, GL_COMPILE);
glBegin(GL_LINE_STRIP);
for(t = -10 * PI; t <= 10 * PI; t += PI/20.0)
    glVertex3f(20 * cos(t), 20 * sin(t), t);
glEnd();
glEndList();
```

The call `glGenLists(range)` returns an integer which starts a block of size *range* of available display list indices. If a block of size *range* is not available, 0 is returned.

The set of commands to be cached in a display list – a helix-drawing routine in the case of `helixList.cpp` – is grouped between a `glNewList(listName, mode)` and a `glEndList()` statement. The parameter *listName* – `aHelix` in `helixList.cpp` – is the index which identifies the list. The parameter *mode* may be `GL_COMPILE` (only store, as in the program) or `GL_COMPILE_AND_EXECUTE` (store and execute immediately).

Finally, the drawing routine of `helixList.cpp` invokes `glCallList(aHelix)` six times to execute the display list. The `glPushMatrix()-glPopMatrix()` statement pairs, as also the modeling transformations (viz., `glTranslatef()`, `glRotatef()`, `glScalef()`) within these pairs, are used to position and scale copies of the helix. Ignore them if they don't make sense at present. **End**

Click for `multipleLists.cpp` [Program](#) [Windows Project](#)

**Experiment 3.7.** Run `multipleLists.cpp`. See Figure 3.5 for a screenshot. Three display lists are defined in the program: to draw a red triangle, a green rectangle and a blue pentagon, respectively.

The call `glCallLists(n, type, *lists)` causes *n* display list executions (*n* is 6 in the program). The indices of the lists to be executed are

obtained by adding the current display list base – this base is specified by `glListBase(base)` – to the successive offset values of type *type* in the array pointed by *lists*. **End**

Click for `fonts.cpp` **Program Windows Project**

**Experiment 3.8.** Run `fonts.cpp`. Displayed are the various fonts available through the GLUT library. See Figure 3.7. **End**

Click for `mouse.cpp` **Program Windows Project**

**Experiment 3.9.** Run `mouse.cpp`. Click the left mouse button to draw points on the canvas and the right one to exit. Figure 3.8 is a screenshot of “OpenGL” scrawled in points. **End**

Click for `mouseMotion.cpp` **Program Windows Project**

**Experiment 3.10.** Run `mouseMotion.cpp`, which enhances `mouse.cpp` by allowing the user to drag the just-created point using the mouse with the left button still pressed. **End**

Click for `moveSphere.cpp` **Program Windows Project**

**Experiment 3.11.** Run `moveSphere.cpp`, a program we saw earlier in Experiment 2.25, where you can see a screenshot as well. Press the left, right, up and down arrow keys to move the sphere, the space bar to rotate it and ‘r’ to reset.

Note how the `specialKeyInput()` routine is written to enable the arrow keys to change the location of the sphere. Subsequently, this routine is registered in `main()` as the handling routine for non-ASCII entry. **End**

Click for `menus.cpp` **Program Windows Project**

**Experiment 3.12.** Run `menus.cpp`. Press the right mouse button for menu options which allow you to change the color of the initially red square or exit. Figure 3.10 is a screenshot.

A `glutCreateMenu(menu_function)` declaration in the `makeMenu()` routine creates a menu, registers `menu_function()` as its callback function and returns a unique integer identifying the menu – to be used by any higher-level menu which may call the current one.

`glutAddMenuEntry(tag, returned_value)` creates a menu entry titled *tag* which, when clicked, returns *returned\_value* to the callback function *menu\_function()*. The latter, therefore, must be of the form *menu\_function(type\_of\_returned\_value)*.

`glutAddSubMenu(tag, sub_menu)` is similar to `glutAddMenuEntry()`, except that when *tag* is clicked a sub-menu pops up whose ID is *sub\_menu*. Evidently, the statement creating a sub-menu must precede that for a higher-level menu which calls it, as the former's ID *sub\_menu* is needed in order to create the latter.

`glutAttachMenu(button)` attaches the menu to a mouse button. **End**

Click for `lineStipple.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 3.13.** Run `lineStipple.cpp`. Press the space bar to cycle through stipples. A screenshot is shown in Figure 3.11. **End**

Click for `canvas.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 3.14.** Run `canvas.cpp`, a simple program to draw on a flat canvas with menu and mouse functionality.

Left click on an icon to select it. Then left click on the drawing area to draw – click once to draw a point, twice to draw a line or rectangle. Right click for menu options. Figure 3.13 is a screenshot. **End**

Click for `glutObjects.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 3.15.** Run `glutObjects.cpp`. Press the arrow keys to cycle through the various GLUT objects and 'x/X', 'y/Y' and 'z/Z' to turn them. **End**

Click for `clippingPlanes.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 3.16.** Run `clippingPlanes.cpp`, which augments `circularAnnulus.cpp` with two additional clipping planes which can be toggled on and off by pressing '0' and '1', respectively.

The first plane clips off the half-space  $-z + 0.25 < 0$ , i.e.,  $z > 0.25$ , removing the floating white disc of the annulus on the upper-right. The second one clips off the half-space  $x + 0.5y < 60.0$ , which is the space below an angled plane parallel to the *z*-axis. Figure 3.16 is a screenshot of both clipping planes activated. **End**

Click for `hemisphere.cpp` [Program](#) [Windows Project](#)

**Experiment 3.17.** Run `hemisphere.cpp`.

The initial OpenGL window is a square  $500 \times 500$  pixels. Drag a corner to change its shape, making it tall and thin. The hemisphere is distorted to become ellipsoidal (Figure 3.21(a)). Replace the perspective projection statement

```
glFrustum(-5.0, 5.0, -5.0, 5.0, 5.0, 100.0);
```

with

```
gluPerspective(90.0, 1.0, 5.0, 100.0);
```

As this is equivalent to the original `glFrustum()` call, there is still distortion if the window's shape is changed. Next, replace the projection statement with

```
gluPerspective(90.0, (float)w/(float)h, 5.0, 100.0);
```

which sets the aspect ratio of the viewing frustum equal to that of the OpenGL window. Resize the window – the hemisphere is no longer distorted (Figure 3.21(b))! **End**

Click for `viewports.cpp` [Program](#) [Windows Project](#)

**Experiment 3.18.** Run `viewports.cpp` where the screen is split into two viewports with contents a square and a circle, respectively. Figure 3.23 is a screenshot.

A vertical black line is drawn (in the program) at the left end of the second viewport to separate the two. As the aspect ratio of both viewports differs from that of the viewing face, the square and circle are squashed laterally. **End**

Click for `windows.cpp` [Program](#) [Windows Project](#)

**Experiment 3.19.** Run `windows.cpp`, which creates two top-level windows (Figure 3.24). **End**

## Part III

# Movers and Shapers



# CHAPTER 4

## Transformation, Animation and Viewing

Click for [box.cpp](#) [Program](#) [Windows Project](#)

**Experiment 4.1.** Run `box.cpp`, which shows an axis-aligned – i.e., with sides parallel to the coordinate axes – GLUT wireframe box of dimensions  $5 \times 5 \times 5$ . Figure 4.1 is a screenshot. Note the foreshortening – the back of the box appears smaller than the front – because of perspective projection in the viewing frustum specified by the `glFrustum()` statement.

Comment out the statement

```
glTranslatef(0.0, 0.0, -15.0);
```

What do you see now? *Nothing!* We'll explain why momentarily. **End**

Click for [box.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 4.2.** Successively replace the translation command of `box.cpp` with the following, making sure that what you see matches your understanding of where the command places the box. Keep in mind foreshortening, as well as clipping to within the viewing frustum.

1. `glTranslatef(0.0, 0.0, -10.0)`
2. `glTranslatef(0.0, 0.0, -5.0)`
3. `glTranslatef(0.0, 0.0, -25.0)`
4. `glTranslatef(10.0, 10.0, -15.0)`

Click for [box.cpp modified](#)   [Program](#)   [Windows Project](#)

**Experiment 4.3.** Add a scaling command, in particular, replace the modeling transformation block of `box.cpp` with (Block 1\*):

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
glScalef(2.0, 3.0, 1.0);
```

Figure 4.4 is a screenshot – compare with the unscaled box of Figure 4.1.

End

Click for [box.cpp modified](#)   [Program](#)   [Windows Project](#)

**Experiment 4.4.** An object less symmetric than a box is more interesting to work with. How about a teapot? Accordingly, change the modeling transformation and object definition part of `box.cpp` to (Block 2):

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
glScalef(1.0, 1.0, 1.0);

glutWireTeapot(5.0); // Teapot.
```

Of course, `glScalef(1.0, 1.0, 1.0)` does nothing and we see the original unscaled teapot (Figure 4.6).

Next, successively change the scaling parameters by replacing the scaling command with the ones below. In each case make, sure your understanding of the command matches the change that you see in the shape of the teapot.

1. `glScalef(2.0, 1.0, 1.0)`
2. `glScalef(1.0, 2.0, 1.0)`
3. `glScalef(1.0, 1.0, 2.0)`

End

Click for [box.cpp modified](#)   [Program](#)   [Windows Project](#)

**Experiment 4.5.** Replace the cube of `box.cpp` with a square whose sides are not parallel to the coordinate axes. In particular, replace the modeling transformation and object definition part of that program with (Block 3):

---

\*To cut-and-paste you can find the block in text format in the file `chap4codeModifications.txt` in the directory `Code/CodeModifications`.

```

// Modeling transformations.
  glTranslatef(0.0, 0.0, -15.0);
// glScalef(1.0, 3.0, 1.0);

glBegin(GL_LINE_LOOP);
  glVertex3f(4.0, 0.0, 0.0);
  glVertex3f(0.0, 4.0, 0.0);
  glVertex3f(-4.0, 0.0, 0.0);
  glVertex3f(0.0, -4.0, 0.0);
glEnd();

```

See Figure 4.8(a). Verify by elementary geometry that the line loop forms a square with sides of length  $4\sqrt{2}$  angled at  $45^\circ$  to the axes.

Uncomment the scaling. See Figure 4.8(b). The square now seems skewed to a non-rectangular parallelogram. Apply the transformation  $(x, y, z) \mapsto (x, 3y, z)$  to each vertex of the original square to verify that the new shape is indeed a parallelogram. End

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.6.** Add a rotation command by replacing the modeling transformation and object definition part – we prefer a teapot – of `box.cpp` with (Block 4):

```

// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
glRotatef(60.0, 0.0, 0.0, 1.0);

glutWireTeapot(5.0);

```

Figure 4.9 is a screenshot.

The *rotation* command `glRotatef(A, p, q, r)` rotates each point of an object about an axis along the line from the origin  $O = (0, 0, 0)$  to the point  $(p, q, r)$ . The amount of rotation is  $A^\circ$ , measured counter-clockwise when looking *from*  $(p, q, r)$  to the origin. In this experiment, then, the rotation is  $60^\circ$  CCW (counter-clockwise) looking down the  $z$ -axis. End

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.7.** Continuing with Experiment 4.6, successively replace the rotation command with the ones below, in each case trying to match what you see with your understanding of how the command should turn the teapot. (It can occasionally be a bit confusing because of the perspective projection.)

1. `glRotatef(60.0, 0.0, 0.0, -1.0)`

2. `glRotatef(-60.0, 0.0, 0.0, 1.0)`
3. `glRotatef(60.0, 1.0, 0.0, 0.0)`
4. `glRotatef(60.0, 0.0, 1.0, 0.0)`
5. `glRotatef(60.0, 1.0, 0.0, 1.0)`

End

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.8.** Appropriately modify `box.cpp` to compare the effects of each of the following pairs of rotation commands:

1. `glRotatef(60.0, 0.0, 0.0, 1.0)` and `glRotatef(60.0, 0.0, 0.0, 5.0)`
2. `glRotatef(60.0, 0.0, 2.0, 2.0)` and `glRotatef(60.0, 0.0, 3.5, 3.5)`
3. `glRotatef(60.0, 0.0, 0.0, -1.0)` and `glRotatef(60.0, 0.0, 0.0, -7.5)`

There is no difference in each case. One concludes that the rotation command `glRotatef( $A, p, q, r$ )` is equivalent to `glRotatef( $A, \alpha p, \alpha q, \alpha r$ )`, where  $\alpha$  is any *positive* scalar. End

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.9.** Apply three modeling transformations by replacing the modeling transformations block of `box.cpp` with (Block 5):

```
// Modeling transformations.  
glTranslatef(0.0, 0.0, -15.0);  
glTranslatef(10.0, 0.0, 0.0);  
glRotatef(45.0, 0.0, 0.0, 1.0);
```

It seems the box is *first* rotated  $45^\circ$  about the  $z$ -axis and *then* translated right 10 units. See Figure 4.12(a). The first translation `glTranslatef(0.0, 0.0, -15.0)`, of course, serves only to “kick” the box down the  $z$ -axis into the viewing frustum.

Next, interchange the last two transformations, namely, the rightward translation and the rotation, by replacing the modeling transformations block with (Block 6):

```
// Modeling transformations.  
glTranslatef(0.0, 0.0, -15.0);  
glRotatef(45.0, 0.0, 0.0, 1.0);  
glTranslatef(10.0, 0.0, 0.0);
```

It seems that the box is now *first* translated right and *then* rotated about the  $z$ -axis causing it “rise”. See Figure 4.12(b). End

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.10.** Replace the entire display routine of the original `box.cpp` with (Block 10):

```
void drawScene(void)
{
    glClearColor(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 0.0, 0.0);
    glLoadIdentity();

    // Modeling transformations.
    glTranslatef(0.0, 0.0, -15.0);
    // glRotatef(45.0, 0.0, 0.0, 1.0);
    glTranslatef(5.0, 0.0, 0.0);

    glutWireCube(5.0); // Box.

    //More modeling transformations.
    glTranslatef (0.0, 10.0, 0.0);

    glutWireSphere (2.0, 10, 8); // Sphere.

    glFlush();
}
```

See Figure 4.14(a) for a screenshot. The objects are a box and a sphere.

End

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.11.** Continuing with the previous experiment, uncomment the `glRotatef()` statement. Figure 4.14(b) is a screenshot.

Again, the individual placements are fairly straightforward. Working backwards from where it is created we see that, after being translated to (5.0, 10.0, 0.0), the sphere is rotated 45° counter-clockwise about the  $z$ -axis and, of course, finally pushed 15 units in the  $-z$  direction. We’ll not compute the exact final coordinates of its center. The individual placement of the box is simple to parse as well and left to the reader.

It’s the relative placement which is particularly interesting in this case. The sphere is no longer vertically above the box, though the transformation between them is still `glTranslatef(0.0, 10.0, 0.0)`! Before trying to explain what’s going on let’s return to the basics for a moment. End

Click for `box.cpp` modified [Program](#) [Windows Project](#)

**Experiment 4.12.** Repeat Experiment 4.11. The modeling transformation and object definition part are as below (Block 11):

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
glRotatef(45.0, 0.0, 0.0, 1.0);
glTranslatef(5.0, 0.0, 0.0);

glutWireCube(5.0); // Box.

//More modeling transformations.
glTranslatef (0.0, 10.0, 0.0);

glutWireSphere (2.0, 10, 8); // Sphere.
```

First, comment out the last two statements of the first modeling transformations block as below (the first translation is always needed to place the entire scene in the viewing frustum):

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
// glRotatef(45.0, 0.0, 0.0, 1.0);
// glTranslatef(5.0, 0.0, 0.0);

glutWireCube(5.0); // Box.

//More modeling transformations.
glTranslatef (0.0, 10.0, 0.0);

glutWireSphere (2.0, 10, 8); // Sphere.
```

The output is as depicted in Figure 4.16(a).

Next, uncomment `glTranslatef(5.0, 0.0, 0.0)` as below:

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
// glRotatef(45.0, 0.0, 0.0, 1.0);
glTranslatef(5.0, 0.0, 0.0);

glutWireCube(5.0); // Box.

//More modeling transformations.
glTranslatef (0.0, 10.0, 0.0);

glutWireSphere (2.0, 10, 8); // Sphere.
```

The output is as in Figure 4.16(b). Finally, uncomment `glRotatef(45.0, 0.0, 0.0, 1.0)` as follows:

```

// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);
glRotatef(45.0, 0.0, 0.0, 1.0);
glTranslatef(5.0, 0.0, 0.0);

glutWireCube(5.0); // Box.

//More modeling transformations.
glTranslatef (0.0, 10.0, 0.0);

glutWireSphere (2.0, 10, 8); // Sphere.

glFlush();

```

The result is seen in Figure 4.16(c). Figure 4.16 shows the box's local coordinate system as well after each transition. Observe that in this particular system the sphere is *always* 10 units vertically above the box, as one would expect from the `glTranslatef (0.0, 10.0, 0.0)` call between the two.

**End**

Click for [composeTransformations.cpp](#) **Program** **Windows** **Project**

**Experiment 4.13.** Run `composeTransformations.cpp`. Pressing the up arrow key once causes the last statement, viz., `drawBlueMan`, of the following piece of code to be executed:

```

glScalef(1.5, 0.75, 1.0);
glRotatef(30.0, 0.0, 0.0, 1.0);
glTranslatef(10.0, 0.0, 0.0);
drawRedMan; // Also draw grid in his local coordinate system.
glRotatef(45.0, 0.0, 0.0, 1.0);
glTranslatef(20.0, 0.0, 0.0);
drawBlueMan;

```

With each press of the up arrow we go back a statement and successively execute that statement *and* the ones that follow it. The statements executed are written in black text, the rest white. Pressing the down arrow key goes forward a statement. Figure 4.17 is a screenshot after all transformations from the scaling on have been executed.

The torso and arms of both men are aligned along their respective local coordinate axes. The world coordinate axes which never change are drawn in cyan. At the time of the red man's creation also drawn is a  $10 \times 10$  grid of boxes in his local coordinate system, the sides of each box being 5 units long. With each transformation going back from the red man's creation, observe – focus on a point like the blue man's origin and trust your eyes – how the blue man stays static in the red man's local coordinate system. A simple calculation shows that the blue man's origin is actually

at  $(20/\sqrt{2}, 20/\sqrt{2}) \simeq (14.14, 14.14)$  in the red man's system. Even when scaling skews the red man's system so that it's not rectangular any more, the blue man skews the same way as well, staying put in the red system.

End

Click for `box.cpp` modified [Program](#) [Windows Project](#)

**Experiment 4.14.** We want to create a human-like character. Our plan is to start by drawing the torso as an elongated cube and placing a round sphere as its head directly on top of the cube (no neck for now). To this end replace the drawing routine of `box.cpp` with (Block 12):

```
void drawScene(void)
{
    glClear(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 0.0, 0.0);
    glLoadIdentity();

    glTranslatef(0.0, 0.0, -15.0);

    glScalef(1.0, 2.0, 1.0);
    glutWireCube(5.0); // Box torso.

    glTranslatef(0.0, 7.0, 0.0);
    glutWireSphere(2.0, 10, 8); // Spherical head.

    glFlush();
}
```

Our calculations are as follows: (a) the scaled box is  $5 \times 10 \times 5$  and, being centered at the origin, is 5 units long in the  $+y$  direction; (b) the sphere is of radius 2; (c) therefore, if the sphere is translated  $5 + 2 = 7$  in the  $+y$  direction, then it should sit exactly on top of the box (see Figure 4.18(a)).

It doesn't work: the sphere is no longer round and is, moreover, some ways above the box (Figure 4.18(b)). Of course, because the sphere is transformed by `glScalef(1.0, 2.0, 1.0)` as well! So, what to do? A solution is to *isolate* the scaling by placing it within a *push-pop pair* as below (Block 13):

```
void drawScene(void)
{
    glClear(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 0.0, 0.0);
    glLoadIdentity();

    glTranslatef(0.0, 0.0, -15.0);
```

```

    glPushMatrix();
    glScalef(1.0, 2.0, 1.0);
    glutWireCube(5.0); // Box.
    glPopMatrix();

    glTranslatef(0.0, 7.0, 0.0);
    glutWireSphere(2.0, 10, 8); // Sphere.

    glFlush();
}

```

**End**

Click for [rotatingHelix1.cpp](#) **Program** **Windows Project**

**Experiment 4.15.** Run `rotatingHelix1.cpp` where each press of space calls the `increaseAngle()` routine to turn the helix. Note the `glutPostRedisplay()` command in `increaseAngle()` which asks the screen to be redrawn. Keeping the space bar pressed turns the helix continuously. Figure 4.20 is a screenshot.

**End**

Click for [rotatingHelix2.cpp](#) **Program** **Windows Project**

**Experiment 4.16.** Run `rotatingHelix2.cpp`, a slight modification of `rotatingHelix1.cpp`, where pressing space causes the routines `increaseAngle()` and `NULL` (do nothing) to be alternately specified as idle functions.

The speed of animation is determined by the processor speed – in particular, the speed at which frames can be redrawn – and the user cannot influence it.

**End**

Click for [rotatingHelix3.cpp](#) **Program** **Windows Project**

**Experiment 4.17.** Run `rotatingHelix3.cpp`, another modification of `rotatingHelix1.cpp`, where the particular timer function `animate()` is first called from the main routine 5 msec. after the `glutTimerFunc(5, animate, 1)` command there. The parameter value 1 which is passed to `animate()` is not used in this program. The routine `increaseAngle()` called by `animate()` turns the helix as before.

Subsequent calls to `animate()` are made recursively from that routine itself after `animationPeriod` number of msec., by means of its own `glutTimerFunc(animationPeriod, animate, 1)` call. The user can vary the speed of animation by changing the value of `animationPeriod` by pressing the up and down arrow keys.

**End**

Click for [rotatingHelix2.cpp](#) modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.18.** Disable double buffering in `rotatingHelix2.cpp` by replacing `GLUT_DOUBLE` with `GLUT_SINGLE` in the `glutInitDisplayMode()` call in `main`, and replacing `glutSwapBuffers()` in the drawing routine with `glFlush()`. Ghostly is it not?! End

Click for [ballAndTorus.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 4.19.** Run `ballAndTorus.cpp`. Press space to start the ball both flying around (longitudinal rotation) and in and out (latitudinal rotation) of the torus. Press the up and down arrow keys to change the speed of the animation. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to change the viewpoint. Figure 4.21 is a screenshot.

The animation of the ball is interesting and we’ll deconstruct it. Comment out all the modeling transformations in the ball’s block, except the last translation, as follows:

```
// Begin revolving ball.
// glRotatef(longAngle, 0.0, 0.0, 1.0);

// glTranslatef(12.0, 0.0, 0.0);
// glRotatef(latAngle, 0.0, 1.0, 0.0);
// glTranslatef(-12.0, 0.0, 0.0);

glTranslatef(20.0, 0.0, 0.0);

glColor3f(0.0, 0.0, 1.0);
glutWireSphere(2.0, 10, 10);
// End revolving ball.
```

The ball is centered at  $(20, 0, 0)$ , its start position, by `glTranslatef(20.0, 0.0, 0.0)`. See Figure 4.22. There is no animation.

The ball’s intended latitudinal rotation is in and out of the circle  $C_1$  through the middle of the torus.  $C_1$ ’s radius, called the *outer radius* of the torus, is 12.0, as specified by the second parameter of `glutWireTorus(2.0, 12.0, 20, 20)`. Moreover,  $C_1$  is centered at the origin and lies on the  $xy$ -plane. Therefore, ignoring longitudinal motion for now, the latitudinal rotation of the ball *from its start position* is about the line  $L$  through  $(12, 0, 0)$  parallel to the  $y$ -axis ( $L$  is tangent to  $C_1$ ). This rotation will cause the ball’s center to travel along the circle  $C_2$  centered at  $(12, 0, 0)$ , lying on the  $xz$ -plane, of radius 8.

As `glRotatef()` always rotates about a radial axis, how does one obtain the desired rotation about  $L$ , a non-radial line? Employ the Trick (see Example 4.2, if you don’t remember). First, translate left so that  $L$  is aligned along the  $y$ -axis, then rotate about the  $y$ -axis and, finally, reverse the

first translation to bring  $L$  back to where it was. Accordingly, uncomment the corresponding three modeling transformations as below:

```
// Begin revolving ball.
// glRotatef(longAngle, 0.0, 0.0, 1.0);

glTranslatef(12.0, 0.0, 0.0);
glRotatef(latAngle, 0.0, 1.0, 0.0);
glTranslatef(-12.0, 0.0, 0.0);

glTranslatef(20.0, 0.0, 0.0);

glColor3f(0.0, 0.0, 1.0);
glutWireSphere(2.0, 10, 10);
// End revolving ball.
```

Press space to view only latitudinal rotation.

*Note:* The two consecutive translation statements could be combined into one, but then the code would be less easy to parse.

Finally, uncomment `glRotatef(longAngle, 0.0, 0.0, 1.0)` to implement longitudinal rotation about the  $z$ -axis. The angular speed of longitudinal rotation is set to be five times slower than that of latitudinal rotation – see the increments to `latAngle` and `longAngle` in the `animate()` routine. This means the ball winds in and out of the torus five times by the time it completes one trip around it. End

Click for `ballAndTorus.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.20.** We want to add a satellite that tags along with the ball of `ballAndTorus.cpp`. The following piece of code added to the end of the drawing routine – just before `glutSwapBuffers()` – does the job (Block 14):

```
glTranslatef(4.0, 0.0, 0.0);

// Satellite
glColor3f(1.0, 0.0, 0.0);
glutWireSphere(0.5, 5, 5);
```

See Figure 4.23 for a screenshot. For a revolving satellite add the following instead (Block 15):

```
glRotatef(10*latAngle, 0.0, 1.0, 0.0);
glTranslatef(4.0, 0.0, 0.0);

// Satellite
glColor3f(1.0, 0.0, 0.0);
glutWireSphere(0.5, 5, 5);
```

Observe how Proposition 4.1 is being applied in both cases to determine the motion of the satellite *relative to the* ball by means of transformation statements between the two. **End**

Click for `throwBall.cpp` **Program Windows Project**

**Experiment 4.21.** Run `throwBall.cpp`, which simulates the motion of a ball thrown with a specified initial velocity subject to the force of gravity. Figure 4.24 is a screenshot.

Press space to toggle between animation on and off. Press the right/left arrow keys to increase/decrease the horizontal component of the initial velocity, up/down arrow keys to increase/decrease the vertical component of the initial velocity and the page up/down keys to increase/decrease gravitational acceleration. Press ‘r’ to reset. The values of the initial velocity components and of gravitational acceleration are displayed on the screen.

**End**

Click for `ballAndTorusWithFriction.cpp` **Program Windows Project**

**Experiment 4.22.** Run `ballAndTorusWithFriction.cpp`, which modifies `ballAndTorus.cpp` to simulate an invisible viscous medium through which the ball travels.

Press space to apply force to the ball. It has to be kept pressed in order to continue applying force. The ball comes to a gradual halt after the key is released. Increase or decrease the level of applied force by using the up and down arrow keys. Increase or decrease the viscosity of the medium using the page up and down keys. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to rotate the scene.

**End**

Click for `clown3.cpp` modified **Program Windows Project**

**Experiment 4.23.** We start with simply a blue sphere for the head. See `clown1.cpp`, which has the following drawing routine:

```
void drawScene(void)
{
    glClear(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();

    // Place scene in frustum.
    glTranslatef(0.0, 0.0, -9.0);

    // Head.
```

```

    glColor3f(0.0, 0.0, 1.0);
    glutWireSphere(2.0, 20, 20);

    glutSwapBuffers();
}

```

Figure 4.25(a) is a screenshot.

Next, we want a green conical hat. The command `glutWireCone(base, height, slices, stacks)` draws a wireframe cone of base radius *base* and height *height*. The base of the cone lies on the *xy*-plane with its axis along the *z*-axis and its apex pointing in the positive direction of the *z*-axis. See Figure 4.26(a). The parameters *slices* and *stacks* determine the fineness of the mesh (not shown in the figure).

Accordingly, insert the lines

```

// Hat.
glColor3f(0.0, 1.0, 0.0);
glutWireCone(2.0, 4.0, 20, 20);

```

in `clown1.cpp` after the call that draws the sphere, so that the drawing routine becomes (Block 17):

```

void drawScene(void)
{
    glClear(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();

    // Place scene in frustum.
    glTranslatef(0.0, 0.0, -9.0);

    // Head.
    glColor3f(0.0, 0.0, 1.0);
    glutWireSphere(2.0, 20, 20);

    // Hat.
    glColor3f(0.0, 1.0, 0.0);
    glutWireCone(2.0, 5.0, 20, 20);

    glutSwapBuffers();
}

```

Not good! Because of the way `glutWireCone()` aligns, the hat covers the clown's face. This is easily fixed. Translate the hat 2 units up the *z*-axis and rotate it  $-90^\circ$  about the *x*-axis to arrange it on top of the head. Finally, rotate it a rakish  $30^\circ$  about the *z*-axis! Here's the modified drawing routine of `clown1.cpp` at this point (Block 18):

```

void drawScene(void)
{

```

```
glClearColor(GL_COLOR_BUFFER_BIT);
glLoadIdentity();

// Place scene in frustum.
glTranslatef(0.0, 0.0, -9.0);

// Head.
glColor3f(0.0, 0.0, 1.0);
glutWireSphere(2.0, 20, 20);

// Transformations of the hat.
glRotatef(30.0, 0.0, 0.0, 1.0);
glRotatef(-90.0, 1.0, 0.0, 0.0);
glTranslatef(0.0, 0.0, 2.0);

// Hat.
glColor3f(0.0, 1.0, 0.0);
glutWireCone(2.0, 5.0, 20, 20);

glutSwapBuffers();
}
```

Let's add a brim to the hat by attaching a torus to its base. The command `glutWireTorus(inRadius, outRadius, sides, rings)` draws a wireframe torus of inner radius *inRadius* (the radius of a circular section of the torus), and outer radius *outRadius* (the radius of the circle through the middle of the torus). The axis of the torus is along the *z*-axis and it is centered at the origin. See Figure 4.26(b). Insert the call `glutWireTorus(0.2, 2.2, 10, 25)` right after the call that draws the cone, so the drawing routine becomes (Block 19):

```
void drawScene(void)
{
    glClearColor(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();

    // Place scene in frustum.
    glTranslatef(0.0, 0.0, -9.0);

    // Head.
    glColor3f(0.0, 0.0, 1.0);
    glutWireSphere(2.0, 20, 20);

    // Transformations of the hat and brim.
    glRotatef(30.0, 0.0, 0.0, 1.0);
    glRotatef(-90.0, 1.0, 0.0, 0.0);
    glTranslatef(0.0, 0.0, 2.0);

    // Hat.
```

```

    glColor3f(0.0, 1.0, 0.0);
    glutWireCone(2.0, 5.0, 20, 20);

    // Brim.
    glutWireTorus(0.2, 2.2, 10, 25);

    glutSwapBuffers();
}

```

Observe that the brim is drawn suitably at the bottom of the hat and stays there despite modeling transformations between head and hat – a consequence of Proposition 4.1.

To animate, let’s spin the hat about the clown’s head by rotating it around the  $y$ -axis. We rig the space bar to toggle between animation on and off and the up/down arrow keys to change speed. All updates so far are included in `clown2.cpp`. Figure 4.25(b) is a screenshot.

What’s a clown without little red ears that pop in and out?! Spheres will do for ears. An easy way to bring about oscillatory motion is to make use of the function  $\sin(\textit{angle})$  which varies between  $-1$  and  $1$ . Begin by translating either ear a unit distance from the head, and then repeatedly translate each a distance of  $\sin(\textit{angle})$ , incrementing  $\textit{angle}$  each time.

*Note:* A technicality one needs to be aware of in such applications is that angle is measured in *degrees* in OpenGL syntax, e.g., in `glRotatef( $\textit{angle}$ ,  $p$ ,  $q$ ,  $r$ )`, while the C++ math library assumes angles to be given in *radians*. Multiplying by  $\pi/180$  converts degrees to radians.

The ears and head are physically separate, though. Let’s connect them with springs! Helixes are springs. We borrow code from `helix.cpp`, but modify it to make the length of the helix 1, its axis along the  $x$ -axis and its radius 0.25. As the ears move, either helix is scaled along the  $x$ -axis so that it spans the gap between the head and an ear. The completed program is `clown3.cpp`, of which a screenshot is seen in Figure 4.25(c). **End**

Click for `floweringPlant.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 4.24.** Run `floweringPlant.cpp`, an animation of a flower blooming. Press space to start and stop animation, delete to reset, and ‘x/X’, ‘y/Y’ and ‘z/Z’ to change the viewpoint. Figure 4.27 is a screenshot. **End**

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.25.** Replace the translation command `glTranslatef(0.0, 0.0, -15.0)` of `box.cpp` with the viewing command `gluLookAt(0.0, 0.0,`

15.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0) so that the drawing routine is as below (Block 20):

```
void drawScene(void)
{
    glClear(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 0.0, 0.0);
    glLoadIdentity();

    // Viewing transformation.
    gluLookAt(0.0, 0.0, 15.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0);

    glutWireCube(5.0); // Box.

    glFlush();
}
```

There is no change in what is viewed. The commands `glTranslatef(0.0, 0.0, -15.0)` and `gluLookAt(0.0, 0.0, 15.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0)` are exactly equivalent. To understand why, note that `gluLookAt(0.0, 0.0, 15.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0)` places the *eye* at  $(0, 0, 15)$  looking down the *z*-axis toward the *center* at  $(0, 0, 0)$ . Now, compare Figures 4.31(a) and (b): should the box appear different to the viewer in one from the other? *No*, because its position relative to the frustum is the same in both.

The advantage of the command `gluLookAt()` over `glTranslatef()` is that it allows one to write code according to one's conception of where the camera is situated and how it's pointed at the scene. **End**

Click for `boxWithLookAt.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 4.26.** Continue the previous experiment, or run `boxWithLookAt.cpp`, successively changing only the parameters *centerx*, *centery*, *centerz* – the middle three parameters – of the `gluLookAt()` call to the following:

1. 0.0, 0.0, 10.0
2. 0.0, 0.0, -10.0
3. 0.0, 0.0, 20.0
4. 0.0, 0.0, 15.0

**End**

**Experiment 4.27.** Restore the original `boxWithLookAt.cpp` program with its `gluLookAt(0.0, 0.0, 15.0, 0.0, 0.0, 0.0, 1.0, 0.0)` call and, again, first replace the box with a `glutWireTeapot(5.0)`. Run: a screenshot is shown in Figure 4.33(a). Next, successively change the parameters *upx*, *upy*, *upz* – the last three parameters of `gluLookAt()` – to the following:

1. 1.0, 0.0, 0.0
2. 0.0, -1.0, 0.0
3. 1.0, 1.0, 0.0

Screenshots of the successive cases are shown in Figures 4.33(b)-(d). The camera indeed appears to rotate *about* its line of sight, the *z*-axis, so that its up direction points along the *up* vector (*upx*, *upy*, *upz*) each time. **End**

Click for `boxWithLookAt.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.28.** Replace the wire cube of `boxWithLookAt.cpp` with a `glutWireTeapot(5.0)` and replace the `gluLookAt()` call with:

```
gluLookAt(0.0, 0.0, 15.0, 0.0, 0.0, 0.0, 1.0, 1.0, 1.0)
```

The vector  $los = (0.0, 0.0, 0.0) - (15.0, 0.0, 0.0) = (-15.0, 0.0, 0.0)$ , which is down the *z*-axis. The component of  $up = (1.0, 1.0, 1.0)$ , perpendicular to the *z*-axis, is  $(1.0, 1.0, 0.0)$ , which then is the up direction. Is what you see the same as Figure 4.33(d), which, in fact, is a screenshot for `gluLookAt(0.0, 0.0, 15.0, 0.0, 0.0, 0.0, 1.0, 1.0, 0.0)`? **End**

Click for `box.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 4.29.** Replace the display routine of `box.cpp` with (Block 21):

```
void drawScene(void)
{
    glClearColor(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 0.0, 0.0);

    glLoadIdentity();

    // Viewing transformation.
    gluLookAt(0.0, 0.0, 15.0, 15.0, 0.0, 0.0, 0.0, 1.0, 0.0);

    // Modeling transformation block equivalent
    // to the preceding viewing transformation.
    // glRotatef(45.0, 0.0, 1.0, 0.0);
```

```
// glTranslatef(0.0, 0.0, -15.0);  
  
glutWireCube(5.0);  
  
glFlush();  
}
```

Run. Next, both comment out the viewing transformation and uncomment the modeling transformation block following it. Run again. The displayed output, shown in Figure 4.42, is the same in both cases. The reason, as Figures 4.43(a)-(c) explain, is that the viewing transformation is equivalent to the modeling transformation block. In particular, the former is undone by the latter. **End**

Click for `spaceTravel.cpp` **Program Windows Project**

**Experiment 4.30.** Run `spaceTravel.cpp`. The left viewport shows a global view from a fixed camera of a conical spacecraft and 40 stationary spherical asteroids arranged in a  $5 \times 8$  grid. The right viewport shows the view from a front-facing camera attached to the tip of the craft. See Figure 4.46 for a screenshot of the program.

Press the up and down arrow keys to move the craft forward and backward and the left and right arrow keys to turn it. Approximate collision detection is implemented to prevent the craft from crashing into an asteroid.

The asteroid grid can be changed in size by redefining `ROWS` and `COLUMNS`. The probability that a particular row-column slot is filled is specified as a percentage by `FILL_PROBABILITY` – a value less than 100 leads to a non-uniform distribution of asteroids. **End**

Click for `spaceTravel.cpp` modified **Program Windows Project**

**Experiment 4.31.** Run `spaceTravel.cpp` with `ROWS` and `COLUMNS` both increased to 100. The spacecraft begins to respond so slowly to key input that its movement seems clunky, unless, of course, you have a super-fast computer (in which case, increase the values of `ROWS` and `COLUMNS` even more). **End**

Click for `animateMan1.cpp` **Program Windows Project**

**Experiment 4.32.** Run `animateMan1.cpp`. This is a fairly complex program to develop a sequence of key frames for a man-like figure, which can subsequently be animated. In addition to its spherical head, the figure consists of nine box-like body parts which can rotate about their joints. See Figure 4.49. All parts are wireframe. We'll explain the program next. **End**

Click for `animateMan2.cpp` [Program](#) [Windows Project](#)

**Experiment 4.33.** Run `animateMan2.cpp`. This is simply a pared-down version of `animateMan1.cpp`, whose purpose is to animate the sequence of configurations listed in the file `animateManDataIn.txt`, typically generated from the develop mode of `animateMan1.cpp`. Press ‘a’ to toggle between animation on/off. As in `animateMan1.cpp`, pressing the up or down arrow key speeds up or slows down the animation. The camera functionalities via the keys ‘r/R’ and ‘z/Z’ remain as well.

The current contents of `animateManDataIn.txt` cause the man to do a handspring over the ball. Figure 4.51 is a screenshot.

Think of `animateMan1.cpp` as the studio and `animateMan2.cpp` as the movie. **End**

Click for `ballAndTorusShadowed.cpp` [Program](#) [Windows Project](#)

**Experiment 4.34.** Run `ballAndTorusShadowed.cpp`, based on `ballAndTorus.cpp`, but with additional shadows drawn on a checkered floor. Press space to start the ball traveling around the torus and the up and down arrow keys to change its speed. Figure 4.52 is a screenshot. **End**

Click for `selection.cpp` [Program](#) [Windows Project](#)

**Experiment 4.35.** Run `selection.cpp`, which is inspired by a similar program in the red book. It uses selection mode to determine the identity of rectangles, drawn with calls to `drawRectangle()`, which intersect the viewing volume created by the projection statement `glOrtho (-5.0, 5.0, -5.0, 5.0, -5.0, 5.0)`, this being a  $10 \times 10 \times 10$  axis-aligned box centered at the origin. Figure 4.54 is a screenshot. Hit records are output to the command window. In the discussion following, we parse the program carefully. **End**

Click for `ballAndTorusPicking.cpp` [Program](#) [Windows Project](#)

**Experiment 4.36.** Run `ballAndTorusPicking.cpp`, which preserves all the functionality of `ballAndTorus.cpp` upon which it is based and adds the capability of picking the ball or torus with a left click of the mouse. The picked object blushes. See Figure 4.57 for a screenshot. **End**



# CHAPTER 5

## Inside Animation: The Theory of Transformations

Click for `box.cpp` modified [Program](#) [Windows Project](#)

**Experiment 5.1.** Fire up `box.cpp` and insert a rotation command just before the box definition so that the transformation and object definition part of the drawing routine becomes:

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);

glRotatef(90.0, 0.0, 1.0, 1.0);
glutWireCube(5.0); // Box.
```

The rotation command asks to rotate  $90^\circ$  about the line  $l$  from the origin through  $(0, 1, 1)$ . See Figure 5.24(a) for the displayed output.

Let's try now, instead, to use the strategy suggested above to express the given rotation in terms of rotations about the coordinate axes. Figure 5.24(b) illustrates the following simple scheme. Align  $l$  along the  $z$ -axis by rotating it  $45^\circ$  about the  $x$ -axis. Therefore, the given rotation should be equivalent to (1) a rotation of  $45^\circ$  about the  $x$ -axis, followed by (2) a rotation of  $90^\circ$  about the  $z$ -axis followed, finally, by a (3) rotation of  $-45^\circ$  about the  $x$ -axis.

Give it a whirl. Replace the single rotation command `glRotatef(90.0, 0.0, 1.0, 1.0)` with a block of three as follows:

```
// Modeling transformations.
glTranslatef(0.0, 0.0, -15.0);

glRotatef(-45.0, 1.0, 0.0, 0.0);
glRotatef(90.0, 0.0, 0.0, 1.0);
```

```
glRotatef(45.0, 1.0, 0.0, 0.0);  
glutWireCube(5.0); // Box.
```

Seeing is believing, is it not?!

**End**

Click for [manipulateModelviewMatrix.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 5.2.** Run `manipulateModelviewMatrix.cpp`. Figure 5.30 is a screenshot, although in this case we are really more interested in the transformations in the program rather than its visual output.

The `gluLookAt(0.0, 0.0, 10.0, 0.0, 0.0, 0.0, 1.0, 0.0)` statement we understand to multiply the current modelview matrix on the right by the matrix of its equivalent modeling transformation. The current modelview matrix is changed again by the `glMultMatrixf(matrixData)` call, which multiplies it on the right by the matrix corresponding to a rotation of  $45^\circ$  about the  $z$ -axis, equivalent to a `glRotatef(45.0, 0.0, 0.0, 1.0)` call. It's changed one last time by `glScalef(1.0, 2.0, 1.0)`.

The current modelview matrix is output to the command window initially and then after each of the three modelview transformations. We'll discuss next if the four output values match our understanding of the theory. **End**

Click for [shear.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 5.3.** Run `shear.cpp`. Press the left and right arrow keys to move the ball. The box begins to shear when struck by the ball. See Figure 5.34.

The shear matrix is explicitly computed in the code and multiplied from the right into the current modelview matrix via a `glMultMatrix()` call.

**End**

# CHAPTER 6

## Advanced Animation Techniques

Click for `spaceTravel.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 6.1.** Run the program `spaceTravel.cpp` after increasing `ROWS` and `COLUMNS` both to 100 from 8 and 5, respectively. Figure 6.1 is a screenshot. The spacecraft now responds sluggishly to the arrow keys, at least on a typical desktop. You may have to increase even more the values of `ROWS` and `COLUMNS` if yours is exceptionally fast. **End**

Click for `spaceTravelFrustumCulled.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 6.2.** Run `spaceTravelFrustumCulled.cpp`, which enhances `spaceTravel.cpp` with optional quadtree-based frustum culling. Pressing space toggles between frustum culling enabled and disabled. As before, the arrow keys maneuver the craft.

The current size of the asteroid field is  $100 \times 100$ . Dramatic isn't it, the speed-up from frustum culling?!

*Important:* Make sure to place the file `intersectionDetectionRoutines.cpp` in the same directory as `spaceTravelFrustumCulled.cpp`.

*Note:* When the number of asteroids is large, the display may take a while to come up because of pre-processing to build the quadtree structure.

**End**

Click for `eulerAngles.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 6.3.** Run `eulerAngles.cpp`, which shows an L, similar to the one in Figure 6.6(a), whose orientation can be interactively changed.

The original orientation of the L has its long leg lying along the  $z$ -axis and its short leg pointing up parallel to the  $y$ -axis. Pressing ‘x/X’, ‘y/Y’ and ‘z/Z’ changes the L’s Euler angles and delete resets. The Euler angle values are displayed on-screen. Figure 6.7 is a screenshot of the initial configuration. **End**

Click for `interpolateEulerAngles.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 6.4.** Run `interpolateEulerAngles.cpp`, which is based on `eulerAngles.cpp`. It simultaneously interpolates between the tuples  $(0, 0, 0)$  and  $(0, 90, 0)$  and between  $(0, 0, 0)$  and  $(-90, 90, 90)$ . Press the left and right arrow keys to step through the interpolations (delete resets). For the first interpolation (green L) the successive tuples are  $(0, angle, 0)$  and for the second (red L) they are  $(-angle, angle, angle)$ ,  $angle$  changing by 5 at each step in both.

The paths are different! The green L seems to follow the intuitively straighter path by keeping its long leg always on the  $xz$ -plane as it rotates about the  $y$ -axis, while the red L arcs above the  $xz$ -plane, as diagrammed in Figure 6.8. Figure 6.9 is a screenshot of `interpolateEulerAngles.cpp` part way through the interpolation. **End**

Click for `eulerAngles.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 6.5.** Run `eulerAngles.cpp` again.

Press ‘x’ and ‘X’ a few times each – the L turns longitudinally. Reset by pressing delete. Press ‘y’ and ‘Y’ a few times each – the L turns latitudinally. Reset. Press ‘z’ and ‘Z’ a few times each – the L twists. There appear to be three physical *degrees of freedom* of the L derived from rotation about the three coordinate axes: longitudinal, latitudinal and “twisting”.

Now, from the initial configuration of `eulerAngles.cpp` press ‘y’ till  $\beta = 90$ . Next, press ‘z’ or ‘Z’ – the L twists. Then press ‘x’ or ‘X’ – the L still twists! **End**

Click for `quaternionAnimation.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 6.6.** Run `quaternionAnimation.cpp`, which applies the preceding ideas to animate the orientation of our favorite rigid body, an L, with the help of quaternions. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to change the orientation of the blue L, whose current Euler angles are shown on the display. Its start orientation is the currently fixed red L. See Figure 6.14 for a screenshot.

Pressing enter at any time begins an animation of the red L from the start to the blue's current orientation. Press the up and down arrow keys to change the speed and delete to reset. **End**



## Part IV

# Geometry for the Home Office



# CHAPTER 7

## Convexity and Interpolation

Click for `square.cpp` modified [Program](#) [Windows Project](#)

**Experiment 7.1.** Replace the polygon declaration part of our old favorite `square.cpp` with the following (Block 1\*):

```
glBegin(GL_TRIANGLES);
    glColor3f(1.0, 0.0, 0.0);
    glVertex3f(20.0, 20.0, 0.0);
    glColor3f(0.0, 1.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glColor3f(0.0, 0.0, 1.0);
    glVertex3f(80.0, 80.0, 0.0);
glEnd();
```

Observe how OpenGL interpolates vertex color values throughout the triangle. Figure 7.7 is a screenshot. [End](#)

Click for `interpolation.cpp` [Program](#) [Windows Project](#)

**Experiment 7.2.** Run `interpolation.cpp`, which shows the interpolated colors of a movable point inside a triangle with red, green and blue vertices. The triangle itself is drawn white. See Figure 7.8 for a screenshot.

As the arrow keys are used to move the large point, the height of each of the three vertical bars on the left indicates the weight of the respective triangle vertex on the point's location. The color of the large point itself is interpolated (by the program) from those of the vertices. [End](#)

---

\*To cut-and-paste you can find the block in text format in the file `chap7codeModifications.txt` in the directory `Code/CodeModifications`.

Click for `convexHull.cpp` [Program](#) [Windows Project](#)

**Experiment 7.3.** Run `convexHull.cpp`, which shows the convex hull of 8 points on a plane. Use the space bar to select a point and the arrow keys to move it. Figure 7.14 is a screenshot.

*Note:* The program implements a very inefficient (but easily coded) algorithm to compute the convex hull of a set  $F$  as the union of all triangles with vertices in  $F$ . **End**

# CHAPTER 8

## Triangulation

Click for `invalidTriangulation.cpp` [Program](#) [Windows Project](#)

**Experiment 8.1.** Run `invalidTriangulation.cpp`, which implements exactly the invalid triangulation  $\{ABC, DBC, DAE\}$  of the rectangle in Figure 8.3(d). Colors have been arbitrarily fixed for the five vertices  $A-E$ . Press space to interchange the order that  $ABC$  and  $DBC$  appear in the code. Figure 8.4 shows the difference. **End**

Click for `square.cpp` modified [Program](#) [Windows Project](#)

**Experiment 8.2.** Replace the polygon declaration of `square.cpp` with (Block 1<sup>1</sup>):

```
glBegin(GL_POLYGON);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(40.0, 40.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
glEnd();
```

Display it *both* filled and outlined using appropriate `glPolygonMode` calls – you see a non-convex quadrilateral in either case (see Figure 8.7(a)).

Next, keeping the *same* cycle of vertices as above, list them starting with `glVertex3f(80.0, 20.0, 0.0)` instead (Block 2):

```
glBegin(GL_POLYGON);
    glVertex3f(80.0, 20.0, 0.0);
```

---

<sup>1</sup>To cut-and-paste you can find the block in text format in the file `chap8codeModifications.txt` in the directory `Code/CodeModifications`.

```
glVertex3f(40.0, 40.0, 0.0);  
glVertex3f(20.0, 80.0, 0.0);  
glVertex3f(20.0, 20.0, 0.0);  
glEnd();
```

Make sure to display it both filled and outlined. When filled it's a triangle, while outlined it's a non-convex quadrilateral identical to the one output earlier (see Figure 8.7(b))! Because the cyclic order of the vertices is unchanged, shouldn't it be as in Figure 8.7(a) both filled and outlined?

**End**

Click for `tessellateAnnulus.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 8.3.** Run `tessellateAnnulus.cpp`, which uses GLU tessellation routines to triangulate a square annulus, a non-simple non-convex polygon. Press the space bar to see the triangulation (Figure 8.11(a)). Compare with the triangulation we did ourselves of a square annulus in `squareAnnulus1.cpp`.

**End**

Click for `tessellateE.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 8.4.** Run `tessellateE.cpp`. Press space ((Figure 8.11(b)).

**End**

# CHAPTER 9

## Orientation

Click for [square.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 9.1.** Replace the polygon declaration part of `square.cpp` with (Block 1<sup>1</sup>):

```
glPolygonMode(GL_FRONT, GL_LINE);
glPolygonMode(GL_BACK, GL_FILL);
glBegin(GL_POLYGON);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
    glVertex3f(80.0, 80.0, 0.0);
    glVertex3f(20.0, 80.0, 0.0);
glEnd();
```

This simply adds the two `glPolygonMode()` statements to the original `square.cpp`. In particular, they specify that front-facing polygons are to be drawn in outline and back-facing ones filled. Now, the order of the vertices is (20.0, 20.0, 0.0), (80.0, 20.0, 0.0), (80.0, 80.0, 0.0), (20.0, 80.0, 0.0), which appears CCW from the viewing face. Therefore, the square is drawn in outline.

Next, rotate the vertices cyclically so that the declaration becomes (Block 2):

```
glPolygonMode(GL_FRONT, GL_LINE);
glPolygonMode(GL_BACK, GL_FILL);
glBegin(GL_POLYGON);
    glVertex3f(20.0, 80.0, 0.0);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
```

---

<sup>1</sup>To cut-and-paste you can find the block in text format in the file `chap9codeModifications.txt` in the directory `Code/CodeModifications`.

```
    glVertex3f(80.0, 80.0, 0.0);  
    glEnd();
```

As the vertex order remains equivalent to the previous one, the square is still outlined.

Reverse the listing next (Block 3):

```
glPolygonMode(GL_FRONT, GL_LINE);  
glPolygonMode(GL_BACK, GL_FILL);  
glBegin(GL_POLYGON);  
    glVertex3f(80.0, 80.0, 0.0);  
    glVertex3f(80.0, 20.0, 0.0);  
    glVertex3f(20.0, 20.0, 0.0);  
    glVertex3f(20.0, 80.0, 0.0);  
glEnd();
```

The square is drawn filled as the vertex order now appears CW from the front of the viewing box. End

Click for [square.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 9.2.** Replace the polygon declaration part of `square.cpp` with (Block 5)

```
glPolygonMode(GL_FRONT, GL_LINE);  
glPolygonMode(GL_BACK, GL_FILL);  
glBegin(GL_TRIANGLES);  
    // CCW  
    glVertex3f(20.0, 80.0, 0.0);  
    glVertex3f(20.0, 20.0, 0.0);  
    glVertex3f(50.0, 80.0, 0.0);  
  
    //CCW  
    glVertex3f(50.0, 80.0, 0.0);  
    glVertex3f(20.0, 20.0, 0.0);  
    glVertex3f(50.0, 20.0, 0.0);  
  
    // CW  
    glVertex3f(50.0, 20.0, 0.0);  
    glVertex3f(50.0, 80.0, 0.0);  
    glVertex3f(80.0, 80.0, 0.0);  
  
    // CCW  
    glVertex3f(80.0, 80.0, 0.0);  
    glVertex3f(50.0, 20.0, 0.0);  
    glVertex3f(80.0, 20.0, 0.0);  
glEnd();
```

The specification is for front faces to be outlined and back faces filled, but, as the four triangles are not consistently oriented, we see both outlined and filled triangles (Figure 9.11(a)). **End**

Click for `square.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 9.3.** Continuing the previous experiment, next replace the polygon declaration part of `square.cpp` with (Block 6):

```
glPolygonMode(GL_FRONT, GL_LINE);
glPolygonMode(GL_BACK, GL_FILL);
glBegin(GL_TRIANGLE_STRIP);
    glVertex3f(20.0, 80.0, 0.0);
    glVertex3f(20.0, 20.0, 0.0);
    glVertex3f(50.0, 80.0, 0.0);
    glVertex3f(50.0, 20.0, 0.0);
    glVertex3f(80.0, 80.0, 0.0);
    glVertex3f(80.0, 20.0, 0.0);
glEnd();
```

The resulting triangulation is the same as before, but, as it's consistently oriented, we see only outlined front faces. (Figure 9.11(b)). **End**

Click for `squareOfWalls.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 9.4.** Run `squareOfWalls.cpp`, which shows four rectangular walls enclosing a square space. The front faces (the outside of the walls) are filled, while the back faces (the inside) are outlined. Figure 9.12(a) is a screenshot.

The triangle strip of `squareOfWalls.cpp` consists of eight triangles which are consistently oriented, because triangles in a strip are *always* consistently oriented. **End**

Click for `threeQuarterSphere.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 9.5.** Run `threeQuarterSphere.cpp`, which adds one half of a hemisphere to the bottom of the hemisphere of `hemisphere.cpp`. The two polygon mode calls ask the front faces to be drawn filled and back ones outlined. Turn the object about the axes by pressing 'x', 'X', 'y', 'Y', 'z' and 'Z'.

Unfortunately, the ordering of the vertices is such that the outside of the hemisphere appears filled, while that of the half-hemisphere outlined. Figure 9.12(b) is a screenshot. Likely, this would not be intended in a

real design application where one would, typically, expect a consistent look throughout one side.

Such mixing up of orientation is not an uncommon error when assembling an object out of multiple pieces. Fix the problem in the case of `threeQuarterSphere.cpp` in four different ways:

- (a) Replace the loop statement

```
for(i = 0; i <= p/2; i++)
```

of the half-hemisphere with

```
for(i = p/2; i >= 0; i--)
```

to reverse its orientation.

- (b) Interchange the two `glVertex3f()` statements of the half-hemisphere, again reversing its orientation.

- (c) Place the additional polygon mode calls

```
glPolygonMode(GL_FRONT, GL_LINE);  
glPolygonMode(GL_BACK, GL_FILL);
```

before the half-hemisphere so that its back faces are drawn filled.

- (d) Call

```
glFrontFace(GL_CCW)
```

before the hemisphere definition and

```
glFrontFace(GL_CW)
```

before the half-hemisphere to change the front-face default to be CW-facing for the latter.

Of the four, either (a) or (b) is to be preferred because they go to the source of the problem and repair the object, rather than hide it with the help of state variables, as do (c) and (d). **End**

### Experiment 9.6. Make a Möbius band as follows.

Take a long and thin strip of paper and draw two equal rows of triangles on one side to make a triangulation of the strip as in the bottom of Figure 9.13. Turn the strip into a Möbius band by pasting the two end edges together after twisting one 180°. The triangles you drew on the strip now make a triangulation of the Möbius band.

Try next to orient the triangles by simply drawing a curved arrow in each, in a manner such that the entire triangulation is consistently oriented. Were you able to?! **End**

Click for `sphereInBox1.cpp` [Program](#) [Windows Project](#)

**Experiment 9.7.** Run `sphereInBox1.cpp`, which draws a green ball inside a red box. Press up or down arrow keys to open or close the box. Figure 9.15(a) is a screenshot of the box partly open.

Ignore the statements to do with lighting and material properties for now. The command `glCullFace(face)` where *face* can be `GL_FRONT`, `GL_BACK` or `GL_FRONT_AND_BACK`, is used to specify if front-facing or back-facing or all polygons are to be culled. Culling is enabled with a call to `glEnable(GL_CULL_FACE)` and disabled with `glDisable(GL_CULL_FACE)`.

You can see at the bottom of the drawing routine that back-facing triangles of the sphere are indeed culled, which makes the program more efficient because these triangle are hidden in any case behind the front-facing ones.

Comment out the `glDisable(GL_CULL_FACE)` call and open the box. Oops, some sides of the box have disappeared, as you can see in Figure 9.15(b). The reason, of course, is that the state variable `GL_CULL_FACE` is set when the drawing routine is called the first time so that all back-facing triangles, including those belonging to the box, are eliminated on subsequent calls.

**End**

Click for `sphereInBox1.cpp` modified [Program](#) [Windows Project](#)

**Experiment 9.8.** Here's a trick often used in 3D design environments like Maya and Studio Max to open up a closed space. Suppose you've finished designing a box-like room and now want to work on objects inside it. A good way to do this is to remove only the walls that obscure your view of the inside and leave the rest, but the obscuring walls are either *all* front-facing or *all* back-facing, so a cull will do the trick.

Insert the pair of statements

```
glEnable(GL_CULL_FACE);
glCullFace(GL_FRONT);
```

in the drawing routine of `sphereInBox1.cpp` just before `glDrawElements()`. The top and front sides of the box are not drawn, leaving its interior visible. Figure 9.15(c) is a screenshot.

**End**

Click for `squareOfWallsReflected.cpp` [Program](#) [Windows Project](#)

**Experiment 9.9.** Run `squareOfWallsReflected.cpp`, which is `squareOfWalls.cpp` with the following additional block of code, including a `glScalef(-1.0, 1.0, 1.0)` call, to reflect the scene about the *yz*-plane.

```
// Block to reflect the scene about the yz-plane.
if (isReflected)
{
    ...
    glScalef(-1.0, 1.0, 1.0);
    // glFrontFace(GL_CW);
}
else
{
    ...
    // glFrontFace(GL_CCW);
}
```

The original walls are as in Figure 9.16(a). Press space to reflect. Keeping in mind that front faces are filled and back faces outlined, it seems that `glScalef(-1.0, 1.0, 1.0)` not only reflects, but turns the square of walls inside out as well, as you can see in Figure 9.16(b)

Well, of course! The viewer's (default) agreement with OpenGL is that if she perceives a primitive's vertex order as CCW, then she is shown the front, if not the back. Reflection about the  $yz$ -plane, an orientation-reversing Euclidean transformation, flips all perceived orientations, so those primitives whose front the viewer used to see now have their back to her, and vice versa.

We likely want the reflection to transform the primitives but not simultaneously change their orientation. This is easily done by revising the viewer's agreement with OpenGL with a call to `glFrontFace(GL_CW)`. Accordingly, uncomment the two `glFrontFace()` statements in the reflection block. Now the reflection looks right, as shown in Figure 9.16(c). The primitives are clearly still being reflected about the  $yz$ -plane, but front and back stay same. **End**

Part V

Making Things Up



# CHAPTER 10

## Modeling in 3D Space

Click for [parabola.cpp](#) Program Windows Project

**Experiment 10.1.** Compare the outputs of `circle.cpp`, `helix.cpp` and `parabola.cpp`, all drawn in Chapter 2.

The sample is chosen uniformly from the parameter space in all three programs. The output quality is good for both the circle – after pressing ‘+’ a sufficient number of times for a dense enough sample – and the helix. The parabola, however, shows a difference in quality between its curved bottom and straighter sides, the sides becoming smoother more quickly than the bottom. In curves such as this, one may want to sample non-uniformly, in particular, more densely from parts of greater curvature. **End**

Click for [astroid.cpp](#) Program Windows Project

**Experiment 10.2.** Run `astroid.cpp`, which was written by modifying `circle.cpp` to implement the parametric equations

$$x = \cos^3 t, \quad y = \sin^3 t, \quad z = 0, \quad 0 \leq t \leq 2\pi$$

for the astroid of Exercise 10.2. Figure 10.9 is a screenshot. **End**

Click for [cylinder.cpp](#) Program Windows Project

**Experiment 10.3.** Run `cylinder.cpp`, which shows a triangular mesh approximation of a circular cylinder, given by the parametric equations

$$x = f(u, v) = \cos u, \quad y = g(u, v) = \sin u, \quad z = h(u, v) = v,$$

for  $(u, v) \in [-\pi, \pi] \times [-1, 1]$ . Pressing arrow keys changes the fineness of the mesh. Press 'x/X', 'y/Y' or 'z/Z' to turn the cylinder itself. Figure 10.28 is a screenshot. **End**

Click for `helicalPipe.cpp` **Program Windows Project**

**Experiment 10.4.** Without really knowing what to expect (honestly!) we tweaked the parametric equations of the cylinder to the following:

$$x = \cos u + \sin v, \quad y = \sin u + \cos v, \quad z = u, \quad (u, v) \in [-\pi, \pi] \times [-\pi, \pi]$$

It turns out the resulting shape looks like a helical pipe – run `helicalPipe.cpp`. Figure 10.31 is a screenshot.

Functionality is the same as for `cylinder.cpp`: press the arrow keys to coarsen or refine the triangulation and 'x/X', 'y/Y' or 'z/Z' to turn the pipe.

Looking at the equations again, it wasn't too hard to figure out how this particular surface came into being. See the next exercise. **End**

Click for `torus.cpp` **Program Windows Project**

**Experiment 10.5.** Run `torus.cpp`, which applies the parametric equations deduced above in the template of `cylinder.cpp` (simply swapping new `f`, `g` and `h` function definitions into the latter program). The radii of the circular trajectory and the profile circle are set to 2.0 and 0.5, respectively. Figure 10.35 is a screenshot.

Functionality is the same as for `cylinder.cpp`: press the arrow keys to coarsen or refine the triangulation and 'x/X', 'y/Y' or 'z/Z' to turn the torus. **End**

Click for `torusSweep.cpp` **Program Windows Project**

**Experiment 10.6.** Run `torusSweep.cpp`, modified from `torus.cpp` to show the animation of a circle sweeping out a torus. Press space to toggle between animation on and off. Figure 10.36 is a screenshot part way through the animation. **End**

Click for `table.cpp` **Program Windows Project**

**Experiment 10.7.** These equations are implemented in `table.cpp`, again using the template of `cylinder.cpp`. Press the arrow keys to coarsen or refine the triangulation and 'x/X', 'y/Y' or 'z/Z' to turn the table. See Figure 10.39 for a screenshot of the table.

Note that the artifacts at the edges of the table arise because sample points may not map exactly to corners  $(0, -8), (4, -8), \dots, (0, 8)$  of the profile drawn in Figure 10.38(a) – which can be avoided by including always  $t$  values 0, 4, 5, 8, 22, 31, 32 and 42 in the sample grid. **End**

Click for `doublyCurledCone.cpp` [Program](#) [Windows Project](#)

**Experiment 10.8.** The plan above is implemented in `doublyCurledCone.cpp`, again using the template of `cylinder.cpp`, with the value of  $A$  set to  $\pi/4$  and  $a$  to 0.05. Press the arrow keys to coarsen or refine the triangulation and ‘x/X’, ‘y/Y’ or ‘z/Z’ to turn the cone. Figure 10.41 is a screenshot. **End**

Click for `extrudedHelix.cpp` [Program](#) [Windows Project](#)

**Experiment 10.9.** Run `extrudedHelix.cpp`, which extrudes a helix, using yet again the template of `cylinder.cpp`. The parametric equations of the extrusion are

$$x = 4\cos(10\pi u), \quad y = 4\sin(10\pi u), \quad z = 10\pi u + 4v, \quad 0 \leq u, v \leq 1$$

the constants being chosen to size the object suitably. As the equation for  $z$  indicates, the base helix is extruded parallel to the  $z$ -axis. Figure 10.42 is a screenshot. **End**

Click for `bilinearPatch.cpp` [Program](#) [Windows Project](#)

**Experiment 10.10.** Run `bilinearPatch.cpp`, which implements precisely Equation (10.19). Press the arrow keys to refine or coarsen the wireframe and ‘x/X’, ‘y/Y’ or ‘z/Z’ to turn the patch. Figure 10.47 is a screenshot. **End**

Click for `hyperboloid1sheet.cpp` [Program](#) [Windows Project](#)

**Experiment 10.11.** Run `hyperboloid1sheet.cpp`, which draws a triangular mesh approximation of a single-sheeted hyperboloid with the help of the parametrization

$$x = \cos u \sec v, \quad y = \sin u \sec v, \quad z = \tan v, \quad u \in [-\pi, \pi], \quad v \in (-\pi/2, \pi/2)$$

Figure 10.51(a) is a screenshot. In the implementation we restrict  $v$  to  $[-0.4\pi, 0.4\pi]$  to avoid  $\pm\pi/2$  where  $\sec$  is undefined. **End**

Click for `gluQuadrics.cpp` [Program](#) [Windows Project](#)

**Experiment 10.12.** Run `gluQuadrics.cpp` to see all four GLU quadrics. Press the left and right arrow keys to cycle through the quadrics and ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn them. The images in Figure 10.52 were, in fact, generated by this program. [End](#)

Click for `glutObjects.cpp` [Program](#) [Windows Project](#)

**Experiment 10.13.** Run `glutObjects.cpp`, a program we originally saw in Chapter 3. Press the left and right arrow keys to cycle through the various GLUT objects and ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn them. Among other objects you see all five regular polyhedra, both in solid and wireframe. [End](#)

Click for `tetrahedron.cpp` [Program](#) [Windows Project](#)

**Experiment 10.14.** Run `tetrahedron.cpp`. The program draws a wire-frame tetrahedron of edge length  $2\sqrt{2}$  which can be turned using the ‘x/X’, ‘y/Y’ and ‘z/Z’ keys. Figure 10.56 is a screenshot. [End](#)

Click for `bezierCurves.cpp` [Program](#) [Windows Project](#)

**Experiment 10.15.** Run `bezierCurves.cpp`. Press the up and down arrow keys to select an order between 2 and 6 on the first screen. Press enter to proceed to the next screen where the control points initially lie on a straight line. Press space to select a control point and then the arrow keys to move it. Press delete to start over. Figure 10.65 is a screenshot for order 6.

In addition to the black Bézier curve, drawn in light gray is its *control polygon*, the polyline through successive control points. Note how the Bézier curve tries to mimic the shape of its control polygon. [End](#)

Click for `bezierCurveWithEvalCoord.cpp` [Program](#) [Windows Project](#)

**Experiment 10.16.** Run `bezierCurveWithEvalCoord.cpp`, which draws a fixed Bézier curve of order 6. See Figure 10.66 for a screenshot. [End](#)

**Experiment 10.17.** Run `bezierCurveWithEvalMesh.cpp`. This program is the same as `bezierCurveWithEval.cpp` except that, instead of calls to `glEvalCoord1f()`, the pair of statements

```
glMapGrid1f(50, 0.0, 1.0);
glEvalMesh1(GL_LINE, 0, 50);
```

are used to draw the approximating polyline.

The call `glMapGrid1f(n, t1, t2)` specifies an *evenly-spaced* grid of  $n + 1$  sample points in the parameter interval, starting at *t1* and ending at *t2*. The call `glEvalMesh1(mode, p1, p2)` works in tandem with the `glMapGrid1f(n, t1, t2)` call. For example, if *mode* is `GL_LINE`, then it draws a line strip through the mapped sample points, starting with the image of the *p1*th sample point and ending at the image of the *p2*th one, which is a polyline approximation of part of the Bézier curve. **End**

Click for `bezierCurveTangent.cpp` [Program](#) [Windows Project](#)

**Experiment 10.18.** Run `bezierCurveTangent.cpp`. The blue curve may be shaped by selecting a control point with the space key and moving it with the arrow keys. Visually verify that the two curves meet smoothly when their control polygons meet smoothly. Figure 10.68 is a screenshot of such a configuration. **End**

Click for `bezierSurface.cpp` [Program](#) [Windows Project](#)

**Experiment 10.19.** Run `bezierSurface.cpp`, which allows the user herself to shape a Bézier surface by selecting and moving control points originally in a  $6 \times 4$  grid. Drawn in black actually is a  $20 \times 20$  quad mesh approximation of the Bézier surface. Also drawn in light gray is the *control polyhedron*, which is the polyhedral surface with vertices at control points.

Press the space and tab keys to select a control point. Use the left/right arrow keys to move the selected control point parallel to the *x*-axis, the up/down arrow keys to move it parallel to the *y*-axis, and the page up/down keys to move it parallel to the *z*-axis. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn the surface. Figure 10.69 is a screenshot. **End**

Click for `bezierCanoe.cpp` [Program](#) [Windows Project](#)

**Experiment 10.20.** Run `bezierCanoe.cpp`. Repeatedly press the right arrow key for a design process that starts with a rectangular Bézier patch, and then edits the control points in each of three successive steps until a

canoe is formed. The left arrow reverses the process. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn the surface.

The initial configuration is a  $6 \times 4$  array of control points placed in a rectangular grid on the  $xz$ -plane, making a rectangular Bézier patch.

The successive steps are:

- (1) Lift the two end columns of control points up in the  $y$ -direction and bring them in along the  $x$ -direction to fold the rectangle into a deep pocket.
- (2) Push the middle control points of the end columns outwards along the  $x$ -direction to plump the pocket into a “canoe” with its front and back open.
- (3) Bring together the two halves of each of the two end rows of control points to stitch closed the erstwhile open front and back. Figure 10.70 is a screenshot after this step.

End

Click for `torpedo.cpp`   Program   Windows Project

**Experiment 10.21.** Run `torpedo.cpp`, which shows a torpedo composed of a few different pieces, including bicubic Bézier patch propeller blades:

- (i) Body: GLU cylinder.
- (ii) Nose: hemisphere.
- (iii) Three fins: identical GLU partial discs.
- (iv) Backside: GLU disc.
- (v) Propeller stem: GLU cylinder.
- (vi) Three propeller blades: identical bicubic Bézier patches (control points arranged by trial-and-error).

Press space to start the propellers turning. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn the torpedo. Figure 10.73 is a screenshot. End

Click for `fractals.cpp`   Program   Windows Project

**Experiment 10.22.** Run `fractals.cpp`, which draws three different fractal curves – a Koch snowflake, a variant of the Koch snowflake and a tree – all within the framework above, by simply switching source-sequel specs! Press the left/right arrow keys to cycle through the fractals and the up/down arrow keys to change the level of recursion. Figure 10.77 shows all three at level 4. End

## Part VI

# Lights, Camera, Equation



# CHAPTER 11

## Color and Light

Click for `sphereInBox1.cpp` [Program](#) [Windows Project](#)

**Experiment 11.1.** Run again `sphereInBox1.cpp`, which we ran the first time in Section 9.4. Press the up-down arrow keys to open or close the box. Figure 11.17 is a screenshot of the box partly open. We'll use this program as a running example to explain much of the OpenGL lighting and material color syntax. **End**

Click for `lightAndMaterial1.cpp` [Program](#) [Windows Project](#)

**Experiment 11.2.** Run `lightAndMaterial1.cpp`.

The ball's current ambient and diffuse reflectances are identically set to a maximum blue of  $\{0.0, 0.0, 1.0, 1.0\}$ , its specular reflectance to the highest gray level  $\{1.0, 1.0, 1.0, 1.0\}$  (i.e., white), shininess to 50.0 and emission to zero  $\{0.0, 0.0, 0.0, 1.0\}$ .

Press 'a/A' to decrease/increase the ball's blue **A**mbient and diffuse reflectance. Pressing 's/S' decreases/increases the gray level of its **S**pecular reflectance. Pressing 'h/H' decreases/increases its **s**hIniness, while pressing 'e/E' decreases/increases the blue component of the ball's **E**mission.

The program has further functionalities which we'll explain as they become relevant. **End**

Click for `lightAndMaterial2.cpp` [Program](#) [Windows Project](#)

**Experiment 11.3.** Run `lightAndMaterial2.cpp`.

The white light's current diffuse and specular are identically set to a maximum of  $\{1.0, 1.0, 1.0, 1.0\}$  and it gives off zero ambient light. The

green light's attributes are fixed at a maximum diffuse and specular of  $\{0.0, 1.0, 0.0, 1.0\}$ , again with zero ambient. The global ambient is a low intensity gray at  $\{0.2, 0.2, 0.2, 1.0\}$ .

Press 'w' or 'W' to toggle the **W**hite light off and on. Pressing 'g' or 'G' toggles the **G**reen light off and on. Press 'd/D' to decrease/increase the gray level of the white light's **D**iffuse and specular intensity (the ambient intensity never changes from zero). Pressing 'm/M' decreases/increases the gray intensity of the global **aM**ambient. Rotate the white light about the ball by pressing the arrow keys.

The program has more functionality too which we'll need later. **End**

Click for `lightAndMaterial1.cpp` **Program** **Windows Project**

**Experiment 11.4.** Run `lightAndMaterial1.cpp`.

Reduce the specular reflectance of the ball. Both the white and green highlights begin to disappear, as it's the specular components of the reflected lights which appear as specular highlights. **End**

Click for `lightAndMaterial1.cpp` **Program** **Windows Project**

**Experiment 11.5.** Restore the original values of `lightAndMaterial1.cpp`.

Reduce the diffuse reflectance gradually to zero. The ball starts to lose its roundness until it looks flat as a disc. The reason for this is that the ambient intensity, which does not depend on eye or light direction, is uniform across vertices of the ball and cannot, therefore, provide the sense of depth that obtains from a contrast in color values across the surface. Diffuse light, on the other hand, which varies across the surface depending on light direction, can provide an illusion of depth.

Even though there is a specular highlight, sensitive to both eye and light direction, it's too localized to provide much contrast. Reducing the shininess spreads the highlight but the effect is not a realistic perception of depth.

*Moral:* Diffusive reflectance lends three-dimensionality. **End**

Click for `lightAndMaterial1.cpp` **Program** **Windows Project**

**Experiment 11.6.** Restore the original values of `lightAndMaterial1.cpp`.

Now reduce the ambient reflectance gradually to zero. The ball seems to shrink! This is because the vertex normals turn away from the viewer at the now hidden ends of the ball, scaling down the diffuse reflectance there (recall the  $\cos \theta$  term in the diffusive reflectance equation (11.7)). The result is that, with no ambient reflectance to offset the reduction in diffuse, the ends of the ball are dark.

*Moral:* Ambient reflectance provides a level of uniform lighting over a surface. **End**

Click for `lightAndMaterial1.cpp` **Program** **Windows Project**

**Experiment 11.7.** Restore the original values of `lightAndMaterial1.cpp`. Reduce both the ambient and diffuse reflectances to nearly zero. It's like the cat disappearing, leaving only its grin! Specular light is clearly for highlights and not much else. **End**

Click for `lightAndMaterial1.cpp` **Program** **Windows Project**

**Experiment 11.8.** Run `lightAndMaterial1.cpp` with its original values. With it's current high ambient, diffuse and specular reflectances the ball looks a shiny plastic. Reducing the ambient and diffuse reflectances makes for a heavier and less plastic appearance. Restoring the ambient and diffuse to higher values, but reducing the specular reflectance makes it a less shiny plastic. Low values for all three of ambient, diffuse and specular reflectances give the ball a somewhat wooden appearance. **End**

Click for `lightAndMaterial2.cpp` **Program** **Windows Project**

**Experiment 11.9.** Run `lightAndMaterial2.cpp`. Reduce the white light's diffuse and specular intensity to 0. The ball becomes a flat dull blue disc with a green highlight. This is because the ball's ambient (and diffuse) is blue and cannot reflect the green light's diffuse component, losing thereby three-dimensionality. Raising the white global ambient brightens the ball, but it still looks flat in the absence of diffusive light. **End**

Click for **Nate's site**

**Experiment 11.10.** Nate Robins has a bunch of great tutorial programs at the site [96]. This is a good time to run his `lightmaterial` tutorial, which allows the user to control a set of parameters as well. **End**

Click for `spotlight.cpp` **Program** **Windows Project**

**Experiment 11.11.** Run `spotlight.cpp`. The program is primarily to demonstrate spotlighting, the topic of a forthcoming section. Nevertheless,

press the page-up key to see a multi-colored array of spheres. Figure 11.19 is a screenshot.

Currently, the point of interest in the program is the invocation of the color material mode for the front-face ambient and diffuse reflectances by means of the last two statements in the initialization routine, viz.,

```
glEnable(GL_COLOR_MATERIAL);  
glColorMaterial(GL_FRONT, GL_AMBIENT_AND_DIFFUSE);
```

and subsequent coloring of the spheres in the drawing routine by `glColor4f()` statements. End

Click for `litTriangle.cpp` Program Windows Project

**Experiment 11.12.** Run `litTriangle.cpp`, which draws a single triangle, whose front is coded red and back blue, initially front-facing and lit two-sided. Press the left and right arrow keys to turn the triangle and space to toggle two-sided lighting on and off. See Figure 11.21 for screenshots.

Notice how the back face is dark when two-sided lighting is disabled – this is because the normals are pointing oppositely of the way they should be. End

Click for `lightAndMaterial2.cpp` Program Windows Project

**Experiment 11.13.** Press ‘p’ or ‘P’ to toggle between **P**ositional and directional light in `lightAndMaterial2.cpp`.

The white wire sphere indicates the positional light, while the white arrow the incoming directional light. End

Click for `lightAndMaterial1.cpp` Program Windows Project

**Experiment 11.14.** Run `lightAndMaterial1.cpp`. The current values of the constant, linear and quadratic attenuation parameters are 1, 0 and 0, respectively, so there’s no attenuation. Press ‘t/T’ to decrease/increase the quadratic a**T**tenuation parameter. Move the ball by pressing the up/down arrow keys to observe the effect of attenuation. End

Click for `spotlight.cpp` Program Windows Project

**Experiment 11.15.** Run `spotlight.cpp`, which shows a bright white spotlight illuminating a multi-colored array of spheres. A screenshot was shown earlier in Figure 11.19.

Press the page up/down arrows to increase/decrease the angle of the light cone. Press the arrow keys to move the spotlight. A white wire mesh is drawn along the light cone boundary. **End**

Click for `spotlight.cpp` **Program Windows Project**

**Experiment 11.16.** Run again `spotlight.cpp`. The current value of the spotlight's `attenuation` is 2.0, which can be decreased/increased by pressing 't/T'. Note the change in visibility of the balls near the cone boundary as the attenuation changes. **End**

Click for `checkeredFloor.cpp` **Program Windows Project**

**Experiment 11.17.** Run `checkeredFloor.cpp`, which creates a checkered floor drawn as an array of flat shaded triangle strips. See Figure 11.24. Flat shading causes each triangle in the strip to be painted with the color of the last of its three vertices, according to the order of the strip's vertex list. **End**

Click for `sphereInBox1.cpp` **Program Windows Project**

**Experiment 11.18.** Run again `sphereInBox1.cpp`. The normal vector values at the eight box vertices of `sphereInBox1.cpp`, placed in the array `normals[]`, are

$$[\pm 1/\sqrt{3} \ \pm 1/\sqrt{3} \ \pm 1/\sqrt{3}]^T$$

each corresponding to one of the eight possible combinations of signs. **End**

Click for `sphereInBox2.cpp` **Program Windows Project**

**Experiment 11.19.** Run `sphereInBox2.cpp`, which modifies `sphereInBox1.cpp`. Press the arrow keys to open or close the box and space to toggle between two methods of drawing normals.

The first method is that of `sphereInBox1.cpp`, specifying the normal at each vertex as an average of incident face normals. The second creates the box by first drawing one side as a square with the normal at each of its four vertices specified to be the unit vector perpendicular to the square, then placing that square in a display list and, finally, drawing it six times appropriately rotated. Figure 11.32(b) shows the vertex normals to three faces. Figure 11.33 shows screenshots of the box created with and without averaged normals. **End**

Click for `litCylinder.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 11.20.** Run `litCylinder.cpp`, which builds upon `cylinder.cpp` using the normal data calculated above, together with color and a single directional light source. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn the cylinder. The functionality of being able to change the fineness of the mesh approximation has been dropped. Figure 11.37 is a screenshot. **End**

Click for `litDoublyCurledCone.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 11.21.** The program `litDoublyCurledCone.cpp`, in fact, applies the preceding equations for the normal and its length. Press ‘x/X’, ‘y/Y’, ‘z/Z’ to turn the cone. See Figure 11.39 for a screenshot.

As promised, `litDoublyCurledCone.cpp` is pretty much a copy of `litCylinder.cpp`, except for the different `f()`, `g()`, `h()`, `fn()`, `gn()` and `hn()` functions, as also the new `normn()` to compute the normal’s length.

**End**

Click for `litBezierCanoe.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 11.22.** Run `litBezierCanoe.cpp`. Press ‘x/X’, ‘y/Y’, ‘z/Z’ to turn the canoe. You can see a screenshot in Figure 11.40.

This program illuminates the final shape of `bezierCanoe.cpp` of Experiment 10.20 with a single directional light source. Other than the expected command `glEnable(GL_AUTO_NORMAL)` in the initialization routine, an important point to notice about `litBezierCanoe.cpp` is the reversal of the sample grid along the *u*-direction. In particular, compare the statement

```
glMapGrid2f(20, 1.0, 0.0, 20, 0.0, 1.0)
```

of `litBezierCanoe.cpp` with

```
glMapGrid2f(20, 0.0, 1.0, 20, 0.0, 1.0)
```

of `bezierCanoe.cpp`. This change reverses the directions of one of the tangent vectors evaluated at each vertex by OpenGL and, correspondingly, that of the normal (which is the cross-product of the two tangent vectors).

Modify `litBezierCanoe.cpp` by changing

```
glMapGrid2f(20, 1.0, 0.0, 20, 0.0, 1.0);
```

back to `bezierCanoe.cpp`’s

```
glMapGrid2f(20, 0.0, 1.0, 20, 0.0, 1.0);
```

Wrong normal directions! The change from `bezierCanoe.cpp` is necessary. Another solution is to leave `glMapGrid2f()` as it is in `bezierCanoe.cpp`, instead making a call to `glFrontFace(GL_CW)`. **End**

Click for `shipMovie.cpp` [Program](#) [Windows Project](#)

**Experiment 11.23.** Run `shipMovie.cpp`. Pressing space start an animation sequence which begins with a torpedo traveling toward a moving ship and which ends on its own after a few seconds. Figure 11.41 is a screenshot as the torpedo nears the ship.

There are a few different objects. The hull of the ship is obviously inspired by the Bézier canoe of the previous experiment. The deck is a flat Bézier surface – all its control point  $y$ -values are identical – which is designed to fit the hull. Each of the ship’s three storeys is a cylindrical quadric, as is its chimney.

The torpedo should be familiar from the program `torpedo.cpp` of Experiment 10.21. Each of the four grayish boats in the background is a couple of quads, while the sea itself is a solid blue cube.

The smoke from the chimney is a simple-minded *particle system*. In particular, we render a sequence of quadric discs in point mode and hack for it a coloring and animation scheme. **End**

Click for `sizeNormal.cpp` [Program](#) [Windows Project](#)

**Experiment 11.24.** Run `sizeNormal.cpp` based on `litTriangle.cpp`.

The ambient and diffuse colors of the three triangle vertices are set to red, green and blue, respectively. The normals are specified separately as well, initially each of unit length perpendicular to the plane of the triangle.

However, pressing the up/down arrow keys changes (as you can see) the size, but not the direction, of the normal at the red vertex. Observe the corresponding change in color of the triangle. Figure 11.43 is a screenshot. **End**

Click for `sizeNormal.cpp` modified [Program](#) [Windows Project](#)

**Experiment 11.25.** Run `sizeNormal.cpp` after placing the statement `glEnable(GL_NORMALIZE)` at the end of the initialization routine. Press the up/down arrow keys. The triangle no longer changes color (though the white arrow still changes in length, of course, because its size is that of the program-specified normal). **End**



# CHAPTER 12

## Texture

Click for `loadTextures.cpp` [Program](#) [Windows Project](#)

**Experiment 12.1.** Run `loadTextures.cpp`, which loads an external image of a shuttle launch as a texture and generates internally a chessboard image as another.

*Notes:*

1. The `Textures` folder must be placed in the same one as the program is in.
2. Because our programs all use the particular routine `getBMPData()` to read image files, textures applied by them have all to be in the uncompressed 24-bit `bmp` format for which this routine is written. Files in other formats have first to be converted. You can use image-editing software like Windows Paint, GIMP and Adobe Photoshop for this purpose.
3. OpenGL requires that the width and height of a texture be powers of two (in particular, for *unbordered* textures, which is the only kind we'll use). A further requirement is that both dimensions be at least 64; the maximum possible value depends on the implementation. Image files of dimensions not satisfying these conditions have to be resized accordingly. Again, most image-editing software have the capability to do this.

The program paints both the external and the procedural texture onto a square. Figure 12.1 shows the two. Press space to toggle between them, the left and right arrow keys to turn the square and delete to reset it. **End**

Click for `loadTextures.cpp` modified [Program](#) [Windows Project](#)

**Experiment 12.2.** Replace every 1.0 in each `glTexCoord2f()` command of `loadTextures.cpp` with 0.5 so that the polygon specification is (Block 1<sup>1</sup>):

```
glBegin(GL_POLYGON);
    glTexCoord2f(0.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(0.5, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(0.5, 0.5); glVertex3f(10.0, 10.0, 0.0);
    glTexCoord2f(0.0, 0.5); glVertex3f(-10.0, 10.0, 0.0);
glEnd();
```

The lower left quarter of the texture is interpolated over the square (Figure 12.4(a)). Make sure to see both the launch and chessboard textures!

**End**

Click for `loadTextures.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 12.3.** Restore the original `loadTextures.cpp` and delete the last vertex from the polygon so that the specification is that of a triangle (Block 2):

```
glBegin(GL_POLYGON);
    glTexCoord2f(0.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 1.0); glVertex3f(10.0, 10.0, 0.0);
glEnd();
```

Exactly as expected, the lower-right triangular half of the texture is interpolated over the world-space triangle (Figure 12.4(b)).

Change the coordinates of the last vertex of the world-space triangle (Block 3):

```
glBegin(GL_POLYGON);
    glTexCoord2f(0.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 1.0); glVertex3f(0.0, 10.0, 0.0);
glEnd();
```

Interpolation is clearly evident now. Parts of both launch and chessboard are skewed by texturing, as the triangle specified by texture coordinates is not similar to its world-space counterpart (Figure 12.4(c)).

Continuing, change the texture coordinates of the last vertex (Block 4):

```
glBegin(GL_POLYGON);
    glTexCoord2f(0.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(0.5, 1.0); glVertex3f(0.0, 10.0, 0.0);
glEnd();
```

---

<sup>1</sup>To cut-and-paste you can find the block in text format in the file `chap12codeModifications.txt` in the directory `Code/CodeModifications`.

The textures are no longer skewed as the triangle in texture space is similar to the one being textured (Figure 12.4(d)). **End**

Click for `loadTextures.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 12.4.** Restore the original `loadTextures.cpp` and replace `launch.bmp` with `cray2.bmp`, an image of a Cray 2 supercomputer. View the original images in the `Textures` folder and note their sizes: the `launch` is  $512 \times 512$  pixels while the Cray 2 is  $512 \times 256$ . As you can see, the Cray 2 is scaled by half width-wise to fit the square polygon. **End**

Click for `loadTextures.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 12.5.** Restore the original `loadTextures.cpp` and then change the coordinates of only the third world-space vertex of the textured polygon (Block 5):

```
glBegin(GL_POLYGON);
    glTexCoord2f(0.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(1.0, 1.0); glVertex3f(20.0, 0.0, 0.0);
    glTexCoord2f(0.0, 1.0); glVertex3f(-10.0, 10.0, 0.0);
glEnd();
```

The `launch` looks odd. The rocket rises vertically, but the flames underneath are shooting sideways! Toggle to the chessboard and it's instantly clear what's going on. Figure 12.5 shows both textures.

The polygon and the texture have been triangulated *equivalently* – in particular, triangles in the triangulation of one correspond to those in the other via the texture map. Corresponding triangle in this case, though, evidently differ in shape. Subsequently, either triangle of the texture has been *separately* interpolated over the corresponding triangle of the polygon, causing the perceived distortion. See Figure 12.6. **End**

Click for `loadTextures.cpp` modified [Program](#) [Windows](#) [Project](#)

**Experiment 12.6.** Restore the original `loadTextures.cpp` and change the texture coordinates of the polygon as follows (Block 7):

```
glBegin(GL_POLYGON);
    glTexCoord2f(-1.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(2.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(2.0, 2.0); glVertex3f(10.0, 10.0, 0.0);
    glTexCoord2f(-1.0, 2.0); glVertex3f(-10.0, 10.0, 0.0);
glEnd();
```

It seems that the texture space is *tiled* using the texture. See Figure 12.7.

In particular, the texture seems repeated in every unit square of texture space with integer vertex coordinates. As the world-space polygon is mapped to a  $3 \times 2$  rectangle in texture space, it is painted with six copies of the texture, each scaled to an aspect ratio of 2:3. The scheme itself is indicated Figure 12.8. End

[Click for loadTextures.cpp modified](#)   [Program](#)   [Windows](#)   [Project](#)

**Experiment 12.7.** Change the texture coordinates again by replacing each  $-1.0$  with  $-0.5$  (Block 8):

```
glBegin(GL_POLYGON);
    glTexCoord2f(-0.5, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(2.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(2.0, 2.0); glVertex3f(10.0, 10.0, 0.0);
    glTexCoord2f(-0.5, 2.0); glVertex3f(-10.0, 10.0, 0.0);
glEnd();
```

Again it's apparent that the texture space is tiled with the specified texture and that the world-space polygon is painted over with its rectangular image in texture space. End

[Click for loadTextures.cpp modified](#)   [Program](#)   [Windows](#)   [Project](#)

**Experiment 12.8.** Restore the original `loadTextures.cpp` and then change the texture coordinates as below, which is the same as in Experiment 12.6 (Block 7):

```
glBegin(GL_POLYGON);
    glTexCoord2f(-1.0, 0.0); glVertex3f(-10.0, -10.0, 0.0);
    glTexCoord2f(2.0, 0.0); glVertex3f(10.0, -10.0, 0.0);
    glTexCoord2f(2.0, 2.0); glVertex3f(10.0, 10.0, 0.0);
    glTexCoord2f(-1.0, 2.0); glVertex3f(-10.0, 10.0, 0.0);
glEnd();
```

Next, replace the `GL_REPEAT` parameter in the

```
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_WRAP_S, GL_REPEAT);
```

statement of both the `loadExternalTextures()` and `loadProceduralTextures()` routines with `GL_CLAMP` so that it becomes

```
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_WRAP_S, GL_CLAMP);
```

This causes the wrapping mode to be clamped in the *s*-direction. It's probably easiest to understand what happens in this mode by observing in

particular the chessboard texture: see Figure 12.9. Texture  $s$  coordinates greater than 1 are clamped to 1, those less than 0 to 0. Precisely, instead of the texture space being tiled with the texture, points with coordinates  $(s, t)$ , where  $s > 1$ , obtain their color values from the point  $(1, t)$ , while those with coordinates  $(s, t)$ , where  $s < 0$ , obtain them from  $(0, t)$ . **End**

Click for `loadTextures.cpp` modified [Program](#) [Windows Project](#)

**Experiment 12.9.** Continue the previous experiment by clamping the texture along the  $t$ -direction as well. In particular, replace the `GL_REPEAT` parameter in the

```
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_WRAP_T, GL_REPEAT);
```

statement with `GL_CLAMP`. We leave the reader to parse the output. **End**

Click for `fieldAndSky.cpp` [Program](#) [Windows Project](#)

**Experiment 12.10.** Run `fieldAndSky.cpp`, where a grass texture is tiled over a horizontal rectangle and a sky texture clamped to a vertical rectangle. There is the added functionality of being able to transport the camera over the field by pressing the up and down arrow keys. Figure 12.10 shows a screenshot.

As the camera travels, the grass seems to *shimmer – flash* and *scintillate* are terms also used to describe this phenomenon. This is our first encounter with the *aliasing* problem in texturing. Any visual artifact that arises owing to the finite resolution of the display device and the correspondingly “large” size of the individual pixels – at least to the extent that individual ones are discernible by the human eye – is said to be caused by aliasing. **End**

Click for `fieldAndSky.cpp` modified [Program](#) [Windows Project](#)

**Experiment 12.11.** Change to linear filtering in `fieldAndSky.cpp` by replacing every `GL_NEAREST` with `GL_LINEAR`. The grass still shimmers though less severely. The sky seems okay with either `GL_NEAREST` or `GL_LINEAR`. We’ll see next even more powerful filtering options that almost eliminate the problem. **End**

Click for `fieldAndSkyFiltered.cpp` [Program](#) [Windows Project](#)

**Experiment 12.12.** Run `fieldAndSkyFiltered.cpp`, identical to `fieldAndSky.cpp` except for additional filtering options. Press the up/down arrow

keys to move the camera and the left/right ones to cycle through filters for the grass texture. A message at the top left tells the current filter.

Using `gluBuild2DMipmaps()` is straightforward. Simply replace the `glTexImage2D()` command with

```
gluBuild2DMipmaps(GL_TEXTURE_2D, GL_RGB, image[0]->sizeX,  
                 image[0]->sizeY, GL_RGB, GL_UNSIGNED_BYTE,  
                 image[0]->data);
```

to generate all the mipmaps for the base texture in `image[0]`.

The `loadExternalTextures()` routine loads the same grass image as six different textures with the min filter ranging from `GL_NEAREST` to `GL_LINEAR_MIPMAP_LINEAR`. The mag filter used is `GL_NEAREST` when the min filter is `GL_NEAREST` as well; otherwise, it's `GL_LINEAR`. The sky texture is not mipmapped.

As one sees, the more expensive filters do nearly eliminate shimmering, but at the same time tamp down possibly desirable sharpness. For example, blades of grass can be distinguished in Figure 12.14(a), where the weakest filter is applied, but not in Figure 12.14(b), which applies the strongest.

End

Click for [compareFilters.cpp](#) Program Windows Project

**Experiment 12.13.** Run `compareFilters.cpp`, where one sees side-by-side identical images of a shuttle launch bound to a square. Press the up and down arrow keys to move the squares. Press the left arrow key to cycle through filters for the image on the left and the right arrow key to do likewise for the one on the right. Messages at the top say which filters are currently applied. Figure 12.15 is a screenshot of the initial configuration.

Compare, as the squares move, the quality of the textures delivered by the various min filters. If one of the four mipmap-based min filters – `GL_NEAREST_MIPMAP_NEAREST` through `GL_LINEAR_MIPMAP_LINEAR` – is applied, then the particular mipmaps actually used depend on the screen space occupied by the square.

End

Click for [mipmapLevels.cpp](#) Program Windows Project

**Experiment 12.14.** Run `mipmapLevels.cpp`, where mipmaps are supplied by the program, rather than computed automatically with use of `gluBuild2DMipmaps()`. The mipmaps are very simple: just differently colored square images, starting with blue, from size  $64 \times 64$  down to  $1 \times 1$ , created by the routine `createMipmaps()`. Commands of the form

```
glTexImage2D(GL_TEXTURE_2D, level, GL_RGB, width, height,  
            0, GL_RGB, GL_UNSIGNED_BYTE, image);
```

each binds a  $width \times height$  mipmap image to the current texture index, starting with the highest resolution image with *level* parameter 0, and with each successive image of lower resolution having one higher *level* all the way up to 6.

Move the square using the up and down arrow keys. As it grows smaller a change in color indicates a change in the currently applied mipmap. Figure 12.16 is screenshot after the first change. As the min filter setting is `GL_NEAREST_MIPMAP_NEAREST`, a unique color, that of the closest mipmap, is applied to the square at any given time. **End**

Click for `texturedTorus.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 12.15.** Run `texturedTorus.cpp`, which shows a synthetic (red-black) chessboard texture mapped onto a torus. Figure 12.18 is a screenshot. Press space to see animation: the texture scrolls around the torus. The pace of the animation can be changed by pressing the up and down arrow keys. **End**

Click for `texturedTorpedo.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 12.16.** Run `texturedTorpedo.cpp`, which textures parts of the torpedo of `torpedo.cpp` – from Experiment 10.21 – as you can see in the screenshot in Figure 12.20. **End**

Click for `fieldAndSkyLit.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 12.17.** Run `fieldAndSkyLit.cpp`, which applies lighting to the scene of `fieldAndSky.cpp` with help of the `GL_MODULATE` option. The light source is directional – imagine the sun – and its direction controlled using the left and right arrow keys, while its intensity can be changed using the up and down arrow keys. A white line indicates the direction and intensity of the sun. Figure 12.22(a) is a screenshot.

The material colors are all white, as is the light. The normal to the horizontal grassy plane is vertically upwards. Strangely, we use the same normal for the sky’s vertical plane, because using its “true” value toward the positive *z*-direction has the unpleasant, but expected, consequence of a sky that doesn’t darken together with land. **End**

Click for `litTexturedCylinder.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 12.18.** Run `litTexturedCylinder.cpp`, which adds a label texture and a can top texture to `litCylinder.cpp`. Figure 12.22(b) is a screenshot.

Most of the program is routine – the texture coordinate generation is, in fact, a near copy of that in `texturedTorus.cpp` – except for the following lighting model statement which we’re using for the first time:

```
glLightModeli(GL_LIGHT_MODEL_COLOR_CONTROL, GL_SEPARATE_SPECULAR_COLOR)
```

We had briefly encountered this statement as an OpenGL lighting model option in Section 11.4. It causes a modification of OpenGL’s `GL_MODULATE` procedure: the specular color components are separated and not multiplied with the corresponding texture color components, as are the ambient and diffuse, but added in after. The result is that specular highlights are preserved rather than blended with the texture. **End**

# CHAPTER 13

## Special Visual Techniques

Click for [blendRectangles1.cpp](#) [Program](#) [Windows Project](#)

**Experiment 13.1.** Run `blendRectangles1.cpp`, which draws two translucent rectangles with their alpha values equal to 0.5, the red one being closer to the viewer than the blue one. The *code* order in which the rectangles are drawn can be toggled by pressing space. Figure 13.2 shows screenshots of either order. End

Click for [blendRectangles2.cpp](#) [Program](#) [Windows Project](#)

**Experiment 13.2.** Run `blendRectangles2.cpp`, which draws three rectangles at different distances from the eye. The closest one is vertical and a translucent red ( $\alpha = 0.5$ ), the next one is angled and opaque green ( $\alpha = 1$ ), while the farthest is horizontal and a translucent blue ( $\alpha = 0.5$ ). Figure 13.3(a) is a screenshot of the output.

The scene is clearly not authentic as no translucency is evident in either of the two areas where the green and blue rectangles intersect the red. The fault is not OpenGL's as it is rendering as it's supposed to with depth testing. End

Click for [blendRectangles2.cpp modified](#) [Program](#) [Windows Project](#)

**Experiment 13.3.** Rearrange the rectangles and insert two `glDepthMask()` calls in the drawing routine of `blendRectangles2.cpp` as follows:

```
// Draw opaque objects.  
drawGreenRectangle(); // Green rectangle second closest, opaque.
```

```
glDepthMask(GL.FALSE); // Make depth buffer read-only.  
  
// Draw translucent objects.  
drawBlueRectangle(); // Blue rectangle farthest, translucent.  
drawRedRectangle(); // Red rectangle closest to viewer, translucent.  
  
glDepthMask(GL.TRUE); // Make depth buffer writable.
```

Try both `gluLookAt(0.0, 0.0, 3.0, ...)` and `gluLookAt(0.0, 0.0, -3.0, ...)`. Interchange the drawing order of the two translucent rectangles as well. The scene is authentic in every instance. **End**

Click for `sphereInGlassBox.cpp` **Program Windows Project**

**Experiment 13.4.** Run `sphereInGlassBox.cpp`, which makes the sides of the box of `sphereInBox2.cpp` glass-like by rendering them translucently. Only the unaveraged normals option of `sphereInBox2.cpp` is implemented. Press the up and down arrow keys to open or close the box and ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn it.

The opaque sphere is drawn first and then the translucent box sides, after making the depth buffer read-only. A screenshot is Figure 13.5(a). **End**

Click for `fieldAndSkyTexturesBlended.cpp` **Program Windows Project**

**Experiment 13.5.** Run `fieldAndSkyTexturesBlended.cpp`, which is based on `fieldAndSkyLit.cpp`. Press the arrow keys to move the sun. As the sun rises the night sky morphs into a day sky. Figure 13.5(b) shows late evening. The program’s a fairly straightforward application of alpha blending. We point out a few interesting features:

- (a) The sky rectangle is no longer lit as in `fieldAndSkyLit.cpp` because the night texture itself causes the sky to darken.
- (b) Source blending factors all 1 (`GL_ONE`) and destination blending factors all 0 (`GL_ZERO`) enable the grass and night sky textures to initially paint their respective rectangles without dilution.
- (c) The statements

```
if (theta <= 90.0) alpha = theta/90.0;  
else alpha = (180.0 - theta)/90.0;  
glColor4f(1.0, 1.0, 1.0, alpha);
```

in the drawing routine link the `alpha` value to the angle `theta` of the sun in the sky, so that the former increases from 0 to 1 as the sun rises from the horizon to vertically above.

- (d) The day sky is blended into the night sky because both textures paint the same rectangle and because the prior disabling of depth testing allows an incoming fragment to write to a destination pixel, even if its  $z$ -value is equal to the current one (with depth testing on it has to be less in order to do so). The call `glBlendFunc(GL_SRC_ALPHA, GL_ONE_MINUS_SRC_ALPHA)` in the drawing routine sets the source blending factor equal to `alpha` and the destination blending factor to `1 - alpha`. End

Click for `ballAndTorusReflected.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.6.** Run `ballAndTorusReflected.cpp`, which builds on `ballAndTorusShadowed.cpp`. Press space to start the ball traveling around the torus and the up and down arrow keys to change its speed.

The reflected ball and torus are obtained by drawing them scaled by a factor of  $-1$  in the  $y$ -direction, which creates their reflections in the  $xz$ -plane, and then blending the floor into the reflection. Figure 13.5(c) shows a screenshot. End

Click for `fieldAndSkyFogged.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.7.** Run `fieldAndSkyFogged.cpp`, which is based on our favorite workhorse program `fieldAndSky.cpp`, adding to it a movable black ball and controllable fog. Figure 13.6 is a screenshot. There's interaction as well, which we'll describe after discussing next the code and how fog is implemented. End

Click for `billboard.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.8.** Run `billboard.cpp`, where an image of two trees is textured onto a rectangle. Press the up and down arrow keys to move the viewpoint and the space bar to turn billboarding on and off. See Figure 13.9 for screenshots. End

Click for `antiAlias.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.9.** Run `antiAlias.cpp`, which draws a straight line segment which can be rotated with the arrow keys and whose width changed

with the page up/down keys. Press space to toggle between antialiasing off and on. Figure 13.11 shows screenshots of antialiasing both off and on.

Antialiasing is simple to implement in OpenGL. One has to first enable blending. The blending factors `GL_SRC_ALPHA` and `GL_ONE_MINUS_SRC_ALPHA`, used in `antiAlias.cpp`, are the best choice. Antialiasing itself is enabled with a call to

```
glEnable(GL_LINE_SMOOTH)
```

A final point to note in the program is that we ask for the best possible antialiasing with the call

```
glHint(GL_LINE_SMOOTH_HINT, GL_NICEST)
```

**End**

Click for `sphereMapping.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.10.** Run `sphereMapping.cpp`, which shows the scene of a shuttle launch with a reflective rocket cone initially stationary in the sky in front of the rocket. Press the up and down arrow keys to move the cone. As the cone flies down, the reflection on its surface of the launch image changes. Figure 13.13 is a screenshot as it's about to crash to the ground. **End**

Click for `ballAndTorusStenciled.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.11.** Run `ballAndTorusStenciled.cpp`, based on `ballAndTorusReflected.cpp`. The difference is that in the earlier program the entire checkered floor was reflective, while in the current one the red floor is non-reflective except for a mirror-like disc lying on it. Pressing the arrow keys moves the disc and pressing the space key starts and stops the ball moving. As you can see in the screenshot Figure 13.22, the ball and torus are reflected only in the disc and nowhere else. **End**

Click for `bumpMapping.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 13.12.** Run `bumpMapping.cpp`, where a plane is bump mapped to make it appear corrugated. Press space to toggle between bump mapping turned on and off. Figure 13.25 shows screenshots. **End**

## Part VII

# Pixels, Pixels, Everywhere



# CHAPTER 14

## Raster Algorithms

[Click for DDA.cpp](#) [Program](#) [Windows Project](#)

**Experiment 14.1.** Run `DDA.cpp`, which is pretty much a word for word implementation of the DDA algorithm above. A point of note is the *simulation* of the raster by the OpenGL window: the statement `gluOrtho2D(0.0, 500.0, 0.0, 500.0)` identifies pixel-to-pixel the viewing face with the  $500 \times 500$  OpenGL window.

There's no interaction and the endpoints of the line are fixed in the code at  $(100, 100)$  and  $(300, 200)$ . Figure 14.12 is a screenshot. **End**



## Part VIII

# Anatomy of Curves and Surfaces



# CHAPTER 15

## Bézier

Click for `deCasteljau3.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 15.1.** Run `deCasteljau3.cpp`, which shows an animation of de Casteljau’s method for three control points. Press the left or right arrow keys to decrease or increase the curve parameter  $u$ . The interpolating points  $a(u)$ ,  $b(u)$  and  $c(u)$  are colored red, green and blue, respectively. Figure 15.4 is a screenshot. **End**

Click for `bezierCurves.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 15.2.** Run `bezierCurves.cpp`, which allows the user to choose a Bézier curve of order 2-6 and move each control point.

You can choose an order in the first screen by pressing the up and down arrow keys. Select 3. Press enter to go to the next screen to find the control points initially on a straight line. Press space to select a control point – the selected one is red – and then arrow keys to move it. Delete resets to the first screen. Figure 15.5 is a screenshot.

The polygonal line joining the control points, called the *control polygon* of the curve, is drawn in light gray. Evidently, the Bézier curve “mimics” its control polygon, but smoothly, avoiding a corner. **End**

Click for `bezierCurves.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 15.3.** Run `bezierCurves.cpp` and choose order 4 to get a feel for cubic Bézier curves. Note again how the curve mimics its control polygon. **End**

Click for `bezierCurves.cpp` [Program](#) [Windows Project](#)

**Experiment 15.4.** Run `bezierCurves.cpp` and choose the higher orders. It's straightforward to enhance the code for orders even greater than 6. **End**

Click for `bezierCurveTangent.cpp` [Program](#) [Windows Project](#)

**Experiment 15.5.** Run `bezierCurveTangent.cpp`. The second curve may be shaped by selecting a control point with the space bar and moving it with the arrow keys. See Figure 15.10. Visually verify Proposition 15.1(f). **End**

Click for `sweepBezierSurface.cpp` [Program](#) [Windows Project](#)

**Experiment 15.6.** Run `sweepBezierSurface.cpp` to see an animation of the procedure. Press the left/right (or up/down) arrow keys to move the sweeping curve and the space bar to toggle between the two possible sweep directions. Figure 15.14 is a screenshot.

The  $4 \times 4$  array of the Bézier surface's control points (drawn as small squares) consists of a blue, red, green and yellow row of four control points each. The four fixed Bézier curves of order 4 are drawn blue, red, green and yellow, respectively (the curves are in 3-space, which is a bit hard to make out because of the projection). The sweeping Bézier curve is black and its (moving) control points are drawn as larger squares. The currently swept part of the Bézier surface is the dark mesh. The current parameter value is shown at the top left. **End**

Click for `bezierSurface.cpp` [Program](#) [Windows Project](#)

**Experiment 15.7.** Run `bezierSurface.cpp`, which allows the user to shape a Bézier surface by selecting and moving control points. Press the space and tab keys to select a control point. Use the left/right arrow keys to move the control point parallel to the  $x$ -axis, the up/down arrow keys to move it parallel to the  $y$ -axis and the page up/down keys to move it parallel to the  $z$ -axis.

Press 'x/X', 'y/Y' and 'z/Z' to turn the viewpoint. See Figure 15.15 for a screenshot. **End**

# CHAPTER 16

## B-Spline

Click for `bSplines.cpp` [Program](#) [Windows Project](#)

**Experiment 16.1.** Run `bSplines.cpp`, which shows the non-zero parts of the spline functions from first order to cubic over the uniformly spaced knot vector

$$[0, 1, 2, 3, 4, 5, 6, 7, 8]$$

Press the up/down arrow keys to choose the order. Figure 16.9 is a screenshot of the first order. The knot values can be changed as well, but there's no need to now. **End**

Click for `bSplines.cpp` [Program](#) [Windows Project](#)

**Experiment 16.2.** Run again `bSplines.cpp` and select the linear B-splines over the knot vector

$$[0, 1, 2, 3, 4, 5, 6, 7, 8]$$

Figure 16.13 is a screenshot. **End**

Click for `bSplines.cpp` [Program](#) [Windows Project](#)

**Experiment 16.3.** Run again `bSplines.cpp` and select the quadratic B-splines over the knot vector

$$[0, 1, 2, 3, 4, 5, 6, 7, 8]$$

Figure 16.18 is a screenshot. Note the joints indicated as black points. **End**

Click for `quadraticSplineCurve.cpp` [Program](#) [Windows Project](#)

**Experiment 16.4.** Run `quadraticSplineCurve.cpp`, which shows the quadratic spline approximation of nine control points over a uniformly spaced vector of 12 knots. Figure 16.21 is a screenshot.

The control points are green. Press the space bar to select a control point – the selected one turns red – and the arrow keys to move it. The knots are the green points on the black bars at the bottom. At this stage there is no need to change their values. The blue points are the joints of the curve, i.e., images of the knots. Also drawn in light gray is the control polygon. **End**

Click for `bSplines.cpp` [Program](#) [Windows Project](#)

**Experiment 16.5.** Run `bSplines.cpp` and change the order to see a sequence of cubic B-splines. **End**

Click for `cubicSplineCurve1.cpp` [Program](#) [Windows Project](#)

**Experiment 16.6.** Run `cubicSplineCurve1.cpp`, which shows the cubic spline approximation of nine control points over a uniformly-spaced vector of 13 knots. The program is similar to `quadraticSplineCurve.cpp`. See Figure 16.23 for a screenshot.

The control points are green. Press the space bar to select a control point – the selected one is colored red – then the arrow keys to move it. The knots are the green points on the black bars at the bottom. The blue points are the joints of the curve. The control polygon is a light gray. **End**

Click for `bSplines.cpp` [Program](#) [Windows Project](#)

**Experiment 16.7.** Run again `bSplines.cpp`. Change the knot values by selecting one with the space bar and then pressing the left/right arrow keys. Press delete to reset knot values. Note that the routine `Bspline()` implements the CdM formula (and its convention for 0 denominators).

In particular, observe the quadratic and cubic spline functions. Note how they lose their symmetry about a vertical axis through the center, and that no longer are they translates of one another.

Play around with making knot values equal – we'll soon be discussing the utility of multiple knots.

Figures 16.27(a) and (b) are screenshots of the quadratic and cubic functions, respectively, both over the same non-uniform knot vector with a triple knot at the right end. **End**

Click for `quadraticSplineCurve.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 16.8.** Run again `quadraticSplineCurve.cpp`. Press ‘k’ to enter knots mode and alter knot values using the left/right arrow keys and ‘c’ to return to control points mode. Press delete in either mode to reset.

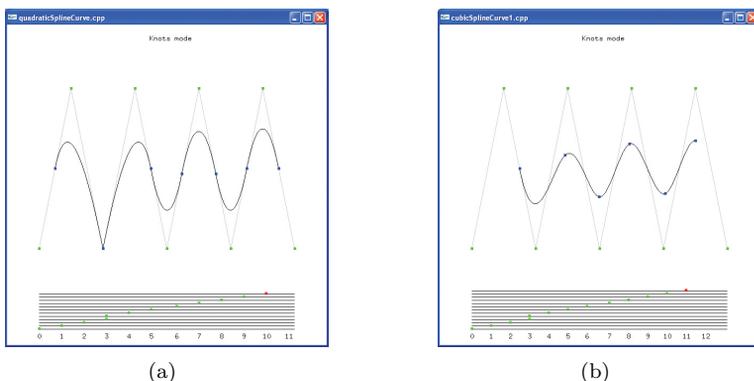
Try to understand what happens if knots are repeated. Do you notice a loss of  $C^1$ -continuity when knots in the interior of the knot vector coincide? What if knots at the ends coincide? Figure 16.28 is a screenshot of `quadraticSplineCurve.cpp` with a double knot at 5 and a triple at the end at 11. **End**

Click for `cubicSplineCurve1.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 16.9.** Run again `cubicSplineCurve1.cpp`. Press ‘k’ to enter knots mode and alter knot values using the left/right arrow keys and ‘c’ to return to control points mode. Press delete in either mode to reset. **End**

Click for `quadraticSplineCurve.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 16.10.** Use the programs `quadraticSplineCurve.cpp` and `cubicSplineCurve1.cpp` to make the quadratic and cubic B-spline approximations over the knot vector  $T = \{0, 1, 2, 3, 3, 4, 5, 6, 7, \dots\}$  of nine control points placed as in Figure 16.31(a) (or (b)). See Figure 16.32(a) and (b) for screenshots of the quadratic and cubic curves, respectively.



**Figure 16.1:** Screenshots of (a) `quadraticSplineCurve.cpp` and (b) `cubicSplineCurve1.cpp` over the knot vector  $T = \{0, 1, 2, 3, 3, 4, 5, 6, 7, \dots\}$  and approximating nine control points arranged in two horizontal rows.

The quadratic approximation loses  $C^1$ -continuity precisely at the control point  $P_2$ , which it now *interpolates* as the curve point  $c(3)$ . It’s still  $C^0$  everywhere.

It's not easy to discern visually, but the cubic spline drops from  $C^2$  to  $C^1$ -continuous at  $c(3)$ . **End**

Click for `cubicSplineCurve1.cpp` **Program Windows Project**

**Experiment 16.11.** Continuing with `cubicSplineCurve1.cpp` with control points as in the preceding experiment, press delete to reset and then make equal  $t_4$ ,  $t_5$  and  $t_6$ , creating a triple knot. Figure 16.33 is a screenshot of this configuration. Evidently, the control point  $P_3$  is now interpolated at the cost of a drop in continuity there to mere  $C^0$ . Elsewhere, the curve is still  $C^2$ . **End**

Click for `quadraticSplineCurve.cpp` **Program Windows Project**

**Experiment 16.12.** Make the first three and last three knots separately equal in `quadraticSplineCurve.cpp` (Figure 16.34(a)). Make the first four and last four knots separately equal in `cubicSplineCurve1.cpp` (Figure 16.34(b)). The first and last control points are interpolated in both. Do you notice any impairment in continuity? *No!* **End**

Click for `quadraticSplineCurve.cpp` **Program Windows Project**

**Experiment 16.13.** Change the last parameter of the statement

```
gluNurbsProperty(nurbsObject, GLU_SAMPLING_TOLERANCE, 10.0);
```

in the initialization routine of `quadraticSplineCurve.cpp` from 10.0 to 100.0. The fall in resolution is noticeable. **End**

Click for `cubicSplineCurve2.cpp` **Program Windows Project**

**Experiment 16.14.** Run `cubicSplineCurve2.cpp`, which draws the cubic spline approximation of 30 movable control points, initially laid out on a circle, over a fixed standard knot vector. Press space and backspace to cycle through the control points and the arrow keys to move the selected control point. The delete key resets the control points. Figure 16.36 is a screenshot of the initial configuration.

The number of control points being much larger than the order, the user has good local control. **End**

**Experiment 16.15.** Run `bicubicSplineSurface.cpp`, which draws a spline surface approximation to a  $15 \times 10$  array of control points, each movable in 3-space. The spline is cubic in both parameter directions and a standard knot vector is specified in each as well.

Press the space, backspace, tab and enter keys to select a control point. Move the selected control point using the arrow and page up and down keys. The delete key resets the control points. Press ‘x/X’, ‘y/Y’ and ‘z/Z’ to turn the surface. Figure 16.38 is a screenshot. **End**

Click for `bicubicSplineSurfaceLitTextured.cpp` [Program](#) [Windows](#)  
[Project](#)

**Experiment 16.16.** Run `bicubicSplineSurfaceLitTextured.cpp`, which textures the spline surface of `bicubicSplineSurface.cpp` with a red-white chessboard texture. Figure 16.39 is a screenshot. The surface is illuminated by a single positional light source whose location is indicated by a large black point. User interaction remains as in `bicubicSplineSurface.cpp`. Note that pressing the ‘x’-‘Z’ keys turns only the surface, not the light source.

The bicubic B-spline surface, as well as the fake bilinear one in texture space, are created by the following statements in the drawing routine:

```
gluBeginSurface(nurbsObject);
gluNurbsSurface(nurbsObject, 19, uknots, 14, vknots,
               30, 3, controlPoints[0][0], 4, 4, GL_MAP2_VERTEX_3);
gluNurbsSurface(nurbsObject, 4, uTextureknots, 4, vTextureknots,
               4, 2, texturePoints[0][0], 2, 2, GL_MAP2_TEXTURE_COORD_2);
gluEndSurface(nurbsObject);
```

We’ll leave the reader to parse in particular the third statement and verify that it creates a “pseudo-surface” – a  $10 \times 10$  rectangle – in texture space on the same parameter domain  $[0, 12] \times [0, 7]$  as the real one. **End**

Click for `trimmedBicubicBsplineSurface.cpp` [Program](#) [Windows](#)  
[Project](#)

**Experiment 16.17.** Run `trimmedBicubicBsplineSurface.cpp`, which shows the surface of `cubicBsplineSurface.cpp` trimmed by multiple loops. The code is modified from `bicubicBsplineSurface.cpp`, functionality remaining same. Figure 16.41(a) is a screenshot. **End**



# CHAPTER 17

## Hermite

Click for [hermiteCubic.cpp](#) [Program](#) [Windows Project](#)

**Experiment 17.1.** Run `hermiteCubic.cpp`, which implements Equation (17.10) to draw a Hermite cubic on a plane. Press space to select either a control point or tangent vector and the arrow keys to change it. Figure 17.4 is a screenshot. The actual cubic is simple to draw, but as you can see in the program we invested many lines of code to get the arrow heads right! **End**



## Part IX

# The Projective Advantage



# CHAPTER 18

## Applications of Projective Spaces

Click for [manipulateProjectionMatrix.cpp](#)    [Program](#)    [Windows](#)  
[Project](#)

**Experiment 18.1.** Run `manipulateProjectionMatrix.cpp`, a simple modification of `manipulateModelviewMatrix.cpp` of Chapter 5. Figure 18.3 is a screenshot, though the output to the OpenGL window is of little interest. Of interest, though, are the new statements in the `resize()` routine that output the current projection matrix just before and after the call `glFrustum(-5.0, 5.0, -5.0, 5.0, 5.0, 100.0)`.

Compare the second matrix output to the command window with  $P(\text{glFrustum}(-5.0, 5.0, -5.0, 5.0, 5.0, 100.0))$  computed with the help of Equation (18.3).    [End](#)

Click for [ballAndTorusPerspectivelyShadowed.cpp](#)    [Program](#)    [Windows](#)  
[Project](#)

**Experiment 18.2.** Run `ballAndTorusPerspectivelyShadowed.cpp`, a program which adds to `ballAndTorusShadowed.cpp` (Experiment 4.34) a back wall, lying along the  $z = -35$  plane, and shadows of the ball and torus cast on it by a light source at the origin. Press space to start the ball traveling around the torus and the up and down arrow keys to change its speed. Figure 18.4 is a screenshot.    [End](#)

Click for [rationalBezierCurve1.cpp](#)    [Program](#)    [Windows](#)    [Project](#)

**Experiment 18.3.** Run `rationalBezierCurve1.cpp`, which draws the cubic rational Bézier curve specified by four control points on the plane at *fixed* locations, but with *changeable* weights.

The control points on the plane (light gray triangular mesh) are all red, except for the currently selected one, which is black. Press space to cycle through the control points. The control point weights are shown at the upper-left, that of the currently selected one being changed by pressing the up/down arrow keys. The rational Bézier curve on the plane is red as well. Figure 18.6 is a screenshot.

Drawn in green are all the lifted control points, except for that of the currently selected control point, which is black. The projective polynomial Bézier curve approximating the lifted control points is green too. The lifted control points are a larger size as well.

*Note:* The lifted control points and the projective Bézier curve are primitives in  $\mathbb{P}^2$ , of course, but represented in  $\mathbb{R}^3$  using their homogeneous coordinates.

Also drawn is a cone of several gray lines through the projective Bézier curve which intersects the plane in its projection, the rational Bézier curve.

Observe that increasing the weight of a control point pulls the (red rational Bézier) curve toward it, while reducing it has the opposite effect. Moreover, the end control points are always interpolated regardless of assigned weights. It's sometimes hard to discern the very gradual change in the shape of the curve as one varies the weights. A trick is to press delete for the curve to spring back to its original configuration, at which moment the difference should be clear.

It seems, then, that the control point weights are an additional set of “dials” at the designer’s disposal for use to edit the curve.

The code of `rationalBezierCurve1.cpp` is instructive as well, as we’ll see in the next section on drawing. **End**

Click for `rationalBezierCurve2.cpp` **Program** **Windows** **Project**

**Experiment 18.4.** Run `rationalBezierCurve2.cpp`, which draws a red quadratic rational Bézier curve on the plane specified by the three control points  $[1, 0]^T$ ,  $[1, 1]^T$  and  $[0, 1]^T$ . See Figure 18.7. Also drawn is the unit circle centered at the origin. Press the up/down arrow keys to change the weight of the middle control point  $[1, 1]^T$ . The weights of the two end control points are fixed at 1.

Decrease the weight of the control point  $[1, 1]^T$  from its initial value of 1.5. It seems that at some value between 0.70 and 0.71 the curve lies exactly along a quarter of the circle (the screenshot of Figure 18.7 is at 1.13). This is no accident, as the following exercise shows. **End**

Click for `rationalBezierCurve3.cpp` **Program** **Windows** **Project**

**Experiment 18.5.** Run `rationalBezierCurve3.cpp`, which shows a rational Bézier curve on the plane specified by six control points. See

Figure 18.8 for a screenshot. A control point is selected by pressing the space key, moved with the arrow keys and its weight changed by the page up/down keys. Pressing delete resets. **End**

Click for [turnFilm2.cpp](#) [Program](#) [Windows Project](#)

**Experiment 18.6.** Run `turnFilm2.cpp`, which animates the snapshot transformation of a polynomial Bézier curve described above. Three control points and their red dashed approximating polynomial Bézier curve are initially drawn on the  $z = 1$  plane. See Figure 18.10(a). The locations of the control points, and so of their approximating curve as well, are *fixed* in world space. However, they will *appear* to move as the film rotates.

Initially, the film lies along the  $z = 1$  plane. Pressing the right arrow key rotates it toward the  $x = 1$  plane, while pressing the left arrow key rotates it back. The film itself, of course, is never seen. As the film changes position, so do the control points and the red dashed curve, these being the *projections* (snapshot transformations, particularly) onto the current film of the control points and their approximating curve (all fixed, as said, in world space). Also drawn on the film is a green dashed curve, which is the polynomial Bézier curve approximating the current projections of the control points.

*Note:* The control points and their approximating curve, all fixed on the  $z = 1$  plane, and corresponding to the control points  $p_0$ ,  $p_1$  and  $p_2$  and the solid red curve in Figure 18.9, are *not* drawn by the program – only their snapshot transformations on the turning film.

Initially, when the plane of the film coincides with that on which the control points are drawn, viz.,  $z = 1$ , the projection onto the film of the polynomial Bézier curve approximating the control points (the red dashed curve) coincides with the polynomial Bézier curve approximating the projected control points (the green dashed curve). This is to be expected because the control points coincide with their projections. However, as the film turns away from the  $z = 1$  plane, the red and green dashed curves begin to separate. Their final configuration, when the film lies along  $x = 1$ , is shown in Figure 18.10(b).

There is more functionality to the program that we'll discuss momentarily. **End**

Click for [turnFilm2.cpp](#) [Program](#) [Windows Project](#)

**Experiment 18.7.** Fire up `turnFilm2.cpp` once again. Pressing space at any time draws, instead of the green dashed curve, a blue dashed *rational* Bézier curve approximating the projected control points on the current plane

of the film. The control point weights of the blue dashed curve are computed according to the strategy just described. Voilà! The blue dashed rational curve and the red dashed projection are inseparable. **End**

Click for `rationalBezierSurface.cpp` **Program** **Windows** **Project**

**Experiment 18.8.** Run `rationalBezierSurface.cpp`, based on `bezierSurface.cpp`, which draws a rational Bézier surface with the functionality that the location and weight of each control point can be changed. Press the space and tab keys to select a control point. Use the arrow and page up/down keys to translate the selected control point. Press '</>' to change its weight. Press delete to reset. The 'x/X', 'y/Y' and 'z/Z' keys turn the viewpoint. Figure 18.12 is a screenshot.

Mark the use of `glMap2f(GL_MAP2_VERTEX_4, ...)`, as also of `glEnable(GL_MAP2_VERTEX_4)`. The 2's in the syntax are for a surface. **End**

## Part X

# The Time is Pipe



# CHAPTER 19

## Fixed-Functionality Pipelines

Click for [box.cpp](#) modified [Program](#) [Windows](#) [Project](#)

**Experiment 19.1.** Replace the `box glutWireCube(5.0)` of `box.cpp` with the line segment

```
glBegin(GL_LINES);
    glVertex3f(1.0, 0.0, -10.0);
    glVertex3f(1.0, 0.0, 0.0);
glEnd();
```

and delete the `glTranslatef(0.0, 0.0, -15.0)` statement. You see a short segment, the clipped part of the defined line segment, whose first endpoint  $[1\ 0\ -10]^T$  is inside the viewing frustum defined by the program's projection statement `glFrustum(-5.0, 5.0, -5.0, 5.0, 5.0, 100.0)`, while the second  $[1\ 0\ 0]^T$  is outside. Figure 19.2 is a screenshot.

Here's what's interesting though – the second endpoint is mapped to a point at infinity by multiplication by OpenGL's projection matrix! This is easy to verify. Simply take the dot product of  $[0\ 0\ -1\ 0]$ , which is the last row of the projection matrix corresponding to `glFrustum(-5.0, 5.0, -5.0, 5.0, 5.0, 100.0)` as given by Equation (18.3), and  $[1\ 0\ 0\ 1]$ , the homogeneous coordinates of the second endpoint, to find that the endpoint's transformed  $w$ -value is 0 (the other coordinate values are irrelevant). **End**

Click for [perspectiveCorrection.cpp](#) [Program](#) [Windows](#) [Project](#)

**Experiment 19.2.** Run `perspectiveCorrection.cpp`. You see a thick straight line segment which starts at a red vertex at its left and ends at a green one at its right. Also seen is a big point just above the line, which can be slid along it by pressing the left/right arrow keys. The point's color can

be changed, as well, between red and green by pressing the up/down arrow keys. Figure 19.4 is a screenshot.

The color-tuple of the segment's left vertex, as you can verify in the code, is  $(1.0, 0.0, 0.0)$ , a pure red, while that of the right is  $(0.0, 1.0, 0.0)$ , a pure green. As expected by interpolation, therefore, there is a color transition from red at the left end of the segment to green at its right.

The number at the topmost right of the display indicates the fraction of the way the big movable point is from the left vertex of the segment to the right. The number below it indicates the fraction of the “way” its color is from red to green – precisely, if the value is  $u$  then the color of the point is  $(1 - u, u, 0)$ .

Initially, the point is at the left and a pure red; in other words, it is 0 distance from the left end, and its color 0 distance from red. Change both values to 0.5 – the color of the point does *not* match that of the segment below it any more. It seems, therefore, that the midpoint of the line is not colored  $(0.5, 0.5, 0.0)$ , which is the color of the point. Shouldn't it be so, though, by linear interpolation, as it is half-way between two end vertices colored  $(1.0, 0.0, 0.0)$  and  $(0.0, 1.0, 0.0)$ , respectively? **End**

*The program `sphereInBoxPOV.pov` is in the folder  
ExperimenterSource/Chapter19/SphereInBoxPOV.*

**Experiment 19.3.** We're going to use POV-Ray (Persistence of Vision Ray Tracer), a freely downloadable ray tracer from [povray.org](http://povray.org) [109]. Download and install POV-Ray. The executable is about 10 MB and there are Linux, Mac OS and Windows versions. It comes packaged with a nicely written tutorial and a reference manual. However, if for some reason you don't want to install POV-Ray, we have a compiled and rendered image file for you to simply open and compare with OpenGL's rendering.

If you have successfully installed POV-Ray, then open `sphereInBoxPOV.pov` from that program; if not, use any editor.

The code itself is fairly self-explanatory. It's written in POV-Ray's scene description language (SDL), which, unlike OpenGL, is *not* a library meant to be called from a C++ program – the SDL is stand-alone. We've obviously tried to follow the settings in our OpenGL program `sphereInBox1.cpp` as far as possible. The camera and a white light source are placed identically as in `sphereInBox1.cpp`. The red box, as in `sphereInBox1.cpp`, is an axis-aligned cube of side lengths two centered at the origin. It comprises six polygonal faces, each originally drawn as a square with vertices at  $(-1, -1)$ ,  $(1, -1)$ ,  $(1, 1)$  and  $(-1, 1)$  on the  $xy$ -plane, and then appropriately rotated and translated. The top face is opened to an angle of  $60^\circ$ . Finally drawn is a green sphere of radius one. The material finishes are minimally complex, just enough to obtain reflection and a specular highlight on the sphere.

If you have installed POV-Ray, then press the Run button at the top;

otherwise, open the output image file `sphereInBoxPOV.jpg` in our Code folder. Figure 19.16(a) is a screenshot. Impressive, is it not, especially if you compare with the output in Figure 19.16(b) of `sphereInBox1.cpp`? The inside of the box, with the interplay of light evident in shadows and reflections, is far more realistic in the ray-traced picture. **End**

*The program `sphereInBoxPOV.pov` is in the folder  
ExperimenterSource/Chapter19/ExperimentRadiosity.*

**Experiment 19.4.** Run again `sphereInBoxPOV.pov`. Then run again after uncommenting the line

```
global_settings{radiosity{}}
```

at the top to enable radiosity computation with default settings. The difference is significant, is it not?

Figure 19.24(a) is the output without radiosity (or see it separately as the image file `sphereInBoxPOV.jpg` in our Code folder), while Figure 19.24(b) is the output with radiosity (`sphereInBoxPOVWithRadiosity.jpg` in Code). There clearly is much more light going around inside the box in the latter rendering. **End**



# CHAPTER 20

## Programmable Pipelines

Click for `redSquare.cpp` [Program](#) [Windows Project](#)

**Experiment 20.1.** Fire up `redSquare.cpp` in the folder `Code/GLSL/Red-Square`.

*Note:* For how to set up the environment to run GLSL programs see Appendix B. Each of our GLSL programs is in a similarly named folder in the GLSL subdirectory of `Code`, with two accompanying shader files. Make sure, when running a GLSL program, to keep it in the same directory as its two shader files.

Now, `redSquare.cpp` is *exactly* `square.cpp` with the *barest* minimum amount of code added to be able to attach a vertex shader, called `passThrough.vs`, and a fragment shader, called `red.fs`. The output is a red square in the OpenGL window, as in Figure 20.2(a). **End**

Click for `redSquare.cpp` – vertex shader modified

[Program](#) [Windows Project](#)

**Experiment 20.2.** Replace the vertex shader code for `redSquare.cpp` with

```
void main()
{
    vec4 scaledPos = vec4(0.5 * gl_Vertex.xy, 0.0, 1.0);
    gl_Position = gl_ModelViewProjectionMatrix * scaledPos;
}
```

As expected, the *xy*-values of the square's vertices are both halved. See Figure 20.2(b) for a screenshot. **End**

Click for `multiColoredSquare1.cpp` [Program](#) [Windows Project](#)

**Experiment 20.3.** Run `multiColoredSquare1.cpp`. The program itself is a copy of `redSquare.cpp`, except for a different color at each square vertex *and* enabling of two-sided coloring with a call to `glEnable(GL_VERTEX_PROGRAM_TWO_SIDE)` in the setup routine. The output initially is a multi-colored square (Figure 20.3(a)).

The vertex shader `simpleColorizer.vs` writes out both a front and a back color to the built-in variables `gl_FrontColor` and `gl_BackColor`, respectively:

```
gl_FrontColor = gl_Color;
gl_BackColor = vec4(1.0, 0.0, 0.0, 1.0);
```

It reads the front color from the user-defined colors, which it accesses through the built-in state variable `gl_Color`, while the back color is a fixed red.

The fragment shader `passThrough.fs`, on the other hand, simply sets

```
gl_FragColor = gl_Color;
```

Now, the way the GLSL works, the fragment shader *does not* receive its `gl_Color` values from the program; rather they are computed by interpolation from either the `gl_FrontColor` or `gl_BackColor` values specified in the vertex shader, depending on the visible face. The use of the same name `gl_Color` to represent actually different variables in the two shaders – the vertex shader using `gl_Color` to access the program, while the fragment shader to access its sibling – can be a source of confusion. One needs to keep the context in mind when using this variable. As the current fragment shader does no more than assign colors interpolated from the vertex shader, it is called a *pass-through* fragment shader.

As the square itself is oriented counter-clockwise and, therefore, front-facing, the fragment shader computes its `gl_Color` values by interpolation from `gl_FrontColor`, which in turn tracks the vertex color values as specified in the program. Consequently, a multi-colored square is drawn.

A fun way to reverse the square's orientation next is with a bit of swizzling. Accordingly, replace the vertex shader code with

```
void main()
{
    gl_FrontColor = gl_Color;
    gl_BackColor = vec4(1.0, 0.0, 0.0, 1.0);

    vec4 transposePos = gl_Vertex.yxzw; // Interchanges x and y
    // coordinate values, reversing the order of the vertices.

    gl_Position = gl_ModelViewProjectionMatrix * transposePos;
}
```

to see now a back-facing red square (Figure 20.3(b)).

**End**

Click for `multiColoredSquare2.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 20.4.** Run `multiColoredSquare2.cpp`. The code is exactly as `redSquare.cpp`, except this time the output is a multi-colored square because of the new shaders. Figure 20.5 is a screenshot. [End](#)

Click for `wavyCylinder1.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 20.5.** Run `wavyCylinder1.cpp`. This program, based on `cylinder.cpp`, draws a cylinder with a wavy surface, allowing the user to control the number of waves, as well as change its color from red to green. Press the up/down arrow keys to change the waviness, the left/right arrow keys to change the color and ‘x’-‘Z’ keys to turn the cylinder. Figure 20.6 shows the cylinder initially. [End](#)

Click for `wavyCylinder2.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 20.6.** Run `wavyCylinder2.cpp`. The output and controls are exactly as for `wavyCylinder1.cpp`. The difference between the two is in the mechanism by which the cross-section of the cylinder is scaled, which we discuss next. [End](#)

Click for `bumpMappingPerVertexLighting.cpp` [Program](#) [Windows](#) [Project](#)

**Experiment 20.7.** Run `bumpMappingPerVertexLighting.cpp`, which is code-wise almost exactly `bumpMapping.cpp`, but with a couple of shaders attached. Interaction is the same as well: press space to toggle between bump mapping on and off. Figures 20.7(a) and (b) are screenshots of `bumpMapping.cpp` and `bumpMappingPerVertexLighting.cpp`, respectively, doing bump mapping. Yes, they are exactly the same and we’ll see momentarily why! [End](#)

Click for `bumpMappingPerVertexLighting.cpp` – vertex shader modified  
[Program](#) [Windows](#) [Project](#)

**Experiment 20.8.** If you are skeptical that we have actually replicated fixed-functionality lighting calculations in the vertex shader `perVertexLightingSimple.vs` and wondering if we are still somehow sneaking the output from fixed-functionality, then replace the `gl.FrontColor` specification in that shader with

```
gl_FrontColor = vec4(1.0, 0.0, 0.0, 1.0);
```

Figure 20.8 is a screenshot. There is no doubt, is there, that it's the vertex shader that's in charge of color calculation?! **End**

Click for [bumpMappingPerPixelLighting.cpp](#) **Program** **Windows**  
**Project**

**Experiment 20.9.** Run `bumpMappingPerPixelLighting.cpp`. The program itself is identical to `bumpMappingPerVertexLighting.cpp` – the difference is in the shaders, which now implement Phong shading, or per-pixel lighting as it is called. Again, press space to toggle between bump mapping on and off. Figure 20.7(c) is a screenshot. **End**

Click for [interpolateTextures.cpp](#) **Program** **Windows** **Project**

**Experiment 20.10.** Run `interpolateTextures.cpp`, which allows the user to interpolate between (or, blend, if you like) two textures painted on a square. Figure 20.9 shows screenshots of the start, a part way and end configurations. **End**

# APPENDIX A

## Projective Spaces and Transformations

Click for [turnFilm1.cpp](#) [Program](#) [Windows Project](#)

**Experiment A.1.** Run `turnFilm1.cpp`, which animates the setting of the preceding exercise by means of a viewing transformation. Initially, the film lies along the  $z = 1$  plane. Pressing the right arrow key rotates it toward the  $x = 1$  plane, while pressing the left one reverses the rotation. Figure A.11 is a screenshot midway. You cannot, of course, see the film, only the view of the lines as captured on it.

The reason that the lower part of the X-shaped image of the power lines cannot be seen is that OpenGL film doesn't capture rays hitting it from behind, as the viewing plane is a clipping plane too. Moreover, if the lines seem to actually meet to make a V after the film turns a certain finite amount, that's because they are very long and your monitor has limited resolution!

This program itself is simple with the one statement of interest being `gluLookAt()`, which we ask the reader to examine next. **End**



# APPENDIX B

## Installing OpenGL and Running Code

(by Chansophea Chuon)

**W**e explain here how to install OpenGL and run the book programs, and create and execute your own, on Windows, Mac OS and Ubuntu Linux platforms.

### B.1 Microsoft Windows XP and Higher

Download and install Microsoft Visual C++ 2010 Express edition from <http://www.microsoft.com/express/>. After Visual C++ has been successfully installed, do the following.

- Install GLUT:
  1. Download and unzip the file `glut-3.7.6-bin.zip` from <http://www.xmission.com/~nate/glut.html>.
    - (a) Copy `glut32.dll` to `C:\Windows\System32`.
    - (b) Copy `glut32.lib` to `C:\Program Files\Microsoft Visual Studio 10.0\VC\lib`
    - (c) Copy `glut.h` to `C:\Program Files\Microsoft Visual Studio 10.0\VC\include\GL`. Note that you may have to create the `GL` directory.
- Install GLEW (if your graphics card supports at least OpenGL 1.5):

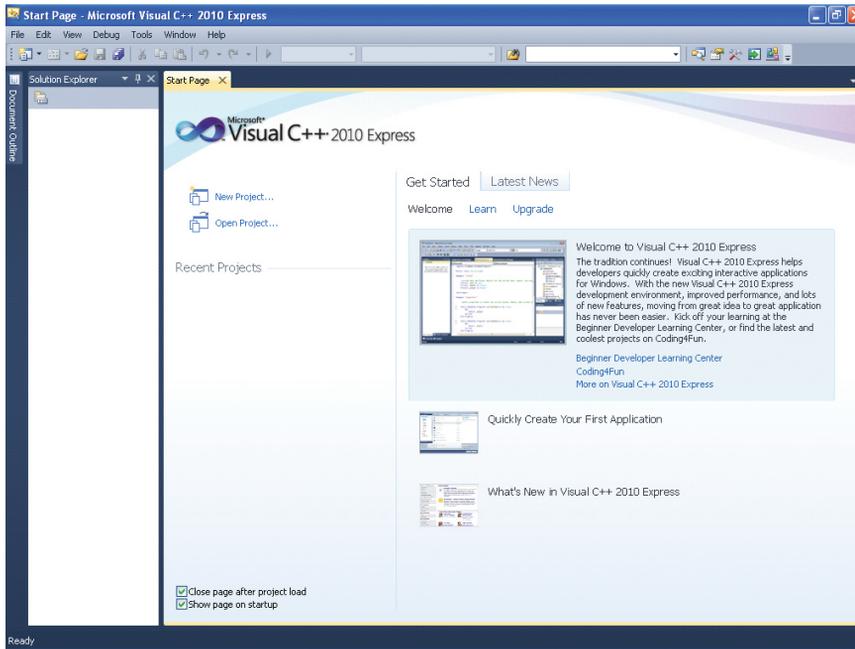
1. Download `glxext.h` from <http://www.opengl.org/registry/api/glxext.h> to `C:\Program Files\Microsoft Visual Studio 10.0\VC\include\GL`.
2. Download and unzip the file `glew-1.5.4-win32.zip` from <http://glew.sourceforge.net/>.
  - (a) Copy `glew32.dll` from the `bin` directory to `C:\Windows\System32`.
  - (b) Copy `glew32.lib` and `glew32s.lib` from the `lib` directory to `C:\Program Files\Microsoft Visual Studio 10.0\VC\lib`
  - (c) Copy `glew.h`, `glxew.h` and `wglew.h` from the `include\GL` directory to `C:\Program Files\Microsoft Visual Studio 10.0\VC\include\GL`.

Now you are ready to run the book programs and write and run your own. Follow the steps in the next pages.

- Open Visual C++ 2010 from the Start Menu to bring up the welcome screen. See Figure B.1.

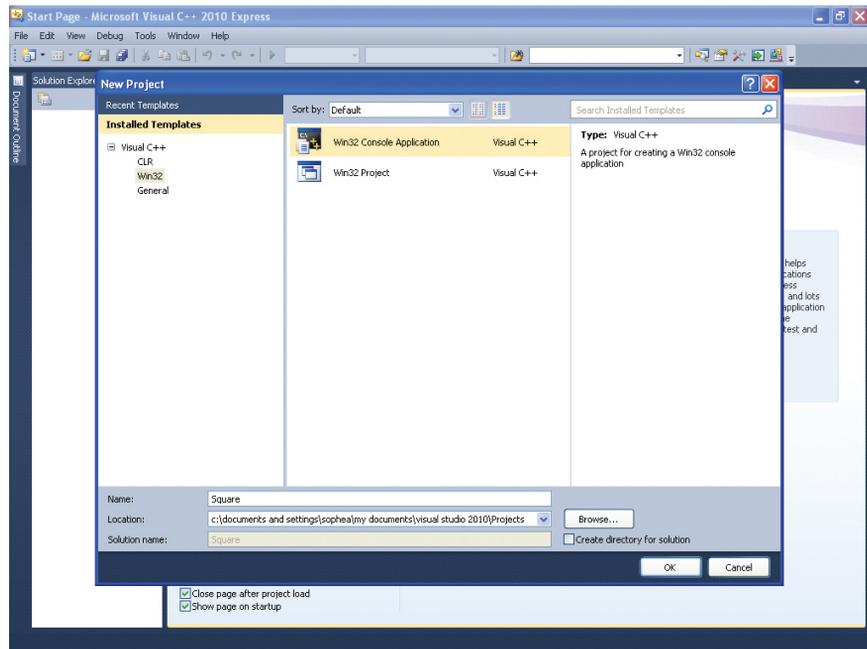
---

**Section B.1**  
MICROSOFT WINDOWS  
XP AND HIGHER



**Figure B.1:** Visual Studio 2010 Express welcome screen.

- Create a new project by going to File → New → Project. See Figure B.2.



**Figure B.2:** New project window.

- Select Win32 from the Installed Templates panel and then Win32 Console Application from the next panel. Name your project and select the folder where you want to save it. Uncheck the box which says “Create directory for solution”. Click OK to bring up a wizard welcome window. See Figure B.3.

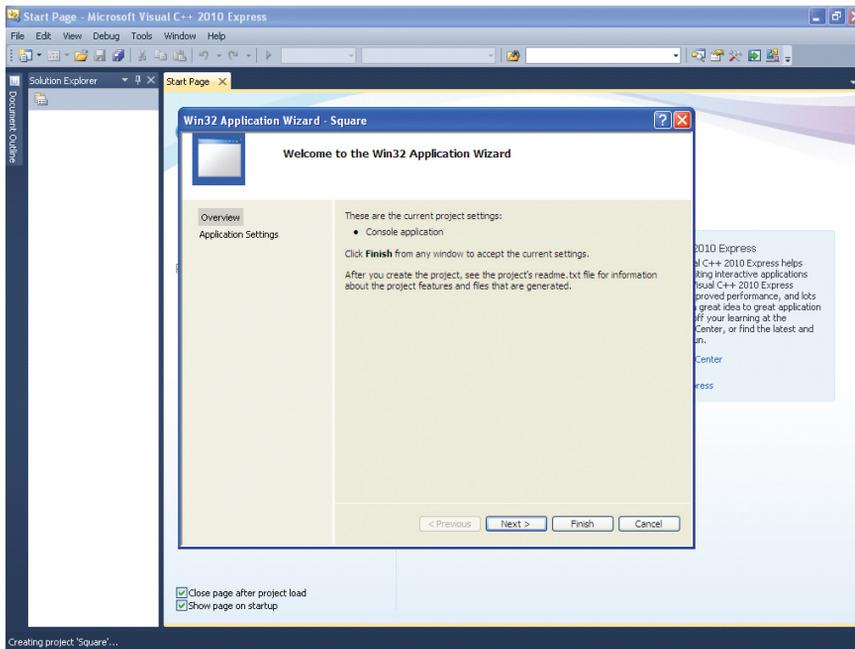


Figure B.3: Win32 application wizard welcome window.

- Click Application Settings for the settings dialog box. See Figure B.4.

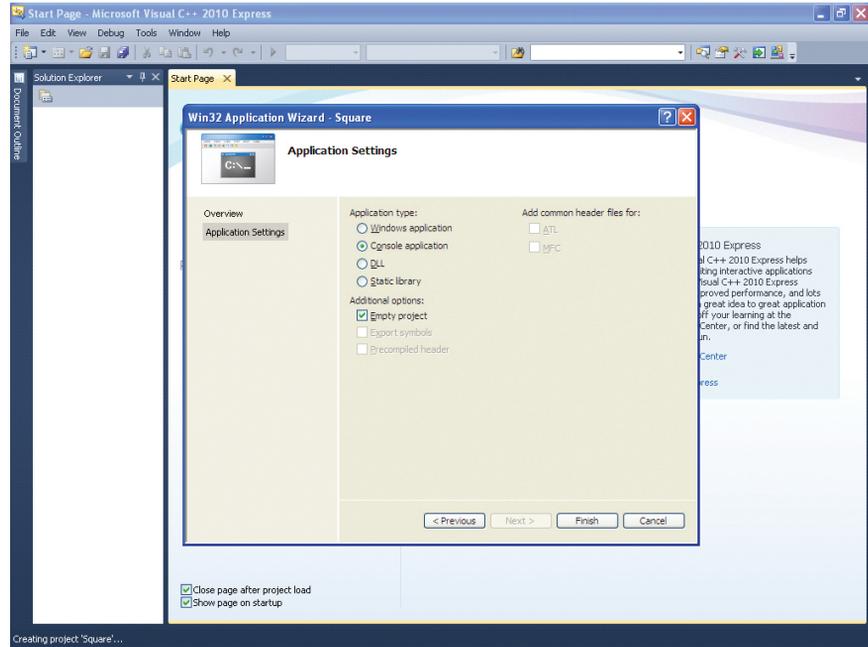
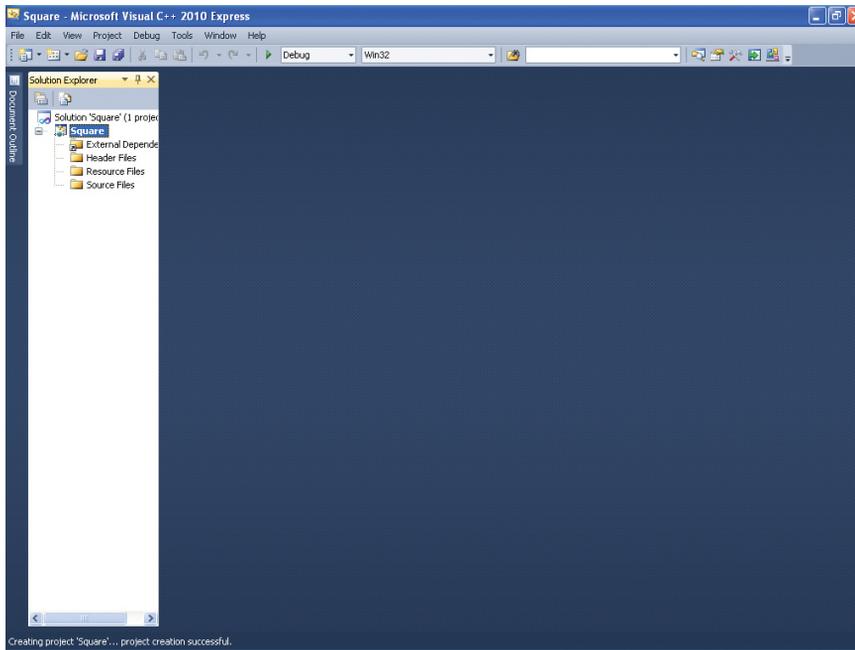


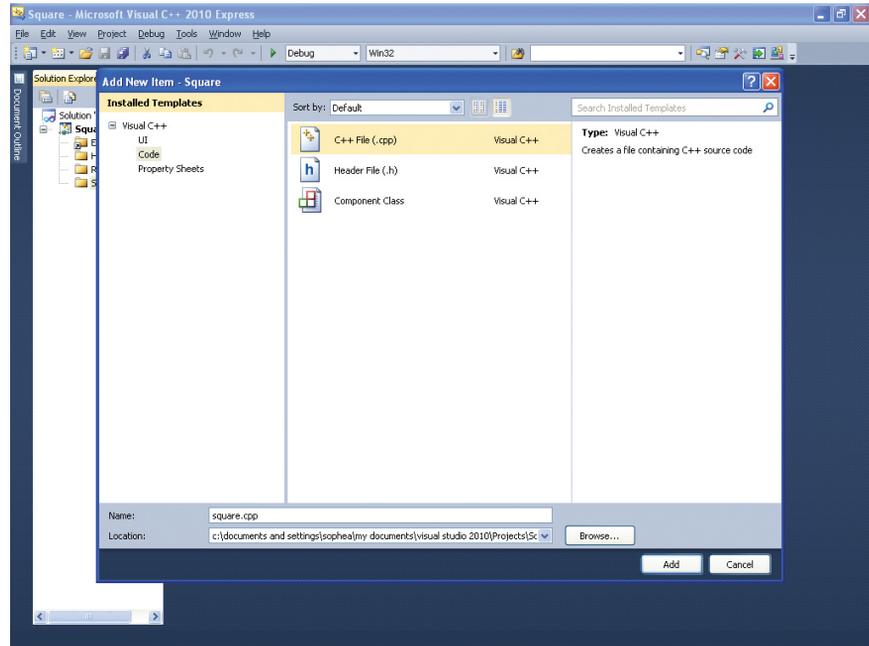
Figure B.4: Win32 application settings dialog box.

- Uncheck the Precompiled header box, check the Empty project box and choose Console application. Click Finish to see a new project window. See Figure B.5



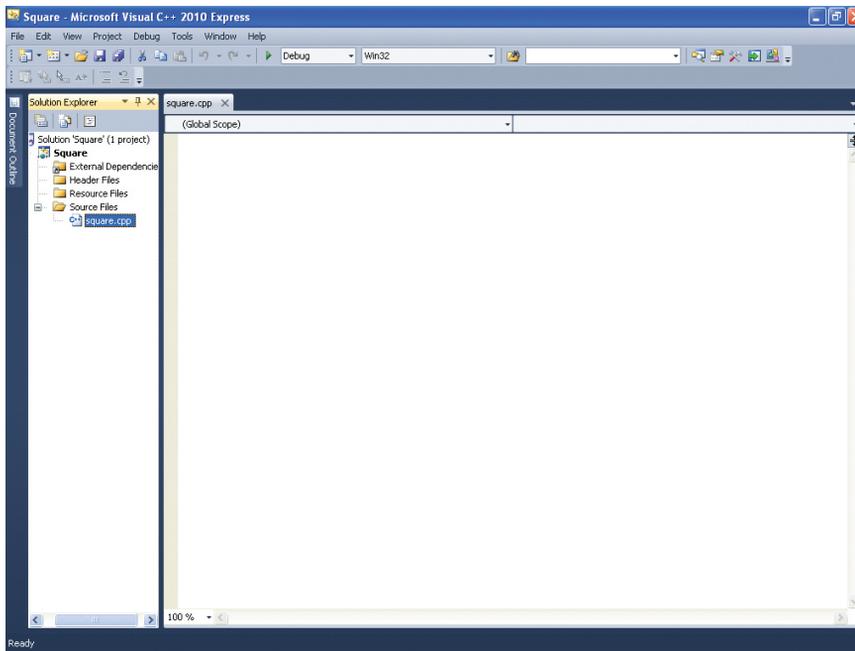
**Figure B.5:** New project window.

- Right click on Source Files and choose Add → New Item to bring up a dialog box. See Figure B.6.



**Figure B.6:** Add new item dialog box.

- Select Code from the Installed Templates panel and C++ File(.cpp) from the next panel. Name your file and click Add to see an empty code panel in the project window titled with your chosen name. See Figure B.7.



**Figure B.7:** Project window with empty code panel.

- Copy any of our book programs into or write your own in the code panel. See Figure B.8.

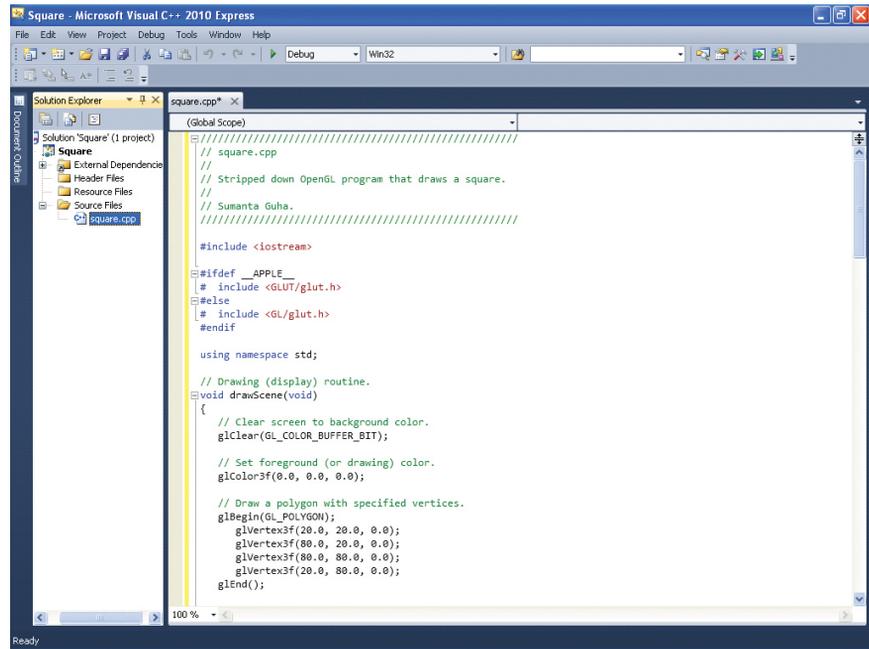


Figure B.8: Code panel with `square.cpp` copied into it.

- Save and build your project by going to Debug → Build Solution. Then execute the program with Debug → Start Debugging. If the program has been built successfully, then you should see no error in the output window.

Congratulations! Output from our `square.cpp` program is shown in Figure B.9.

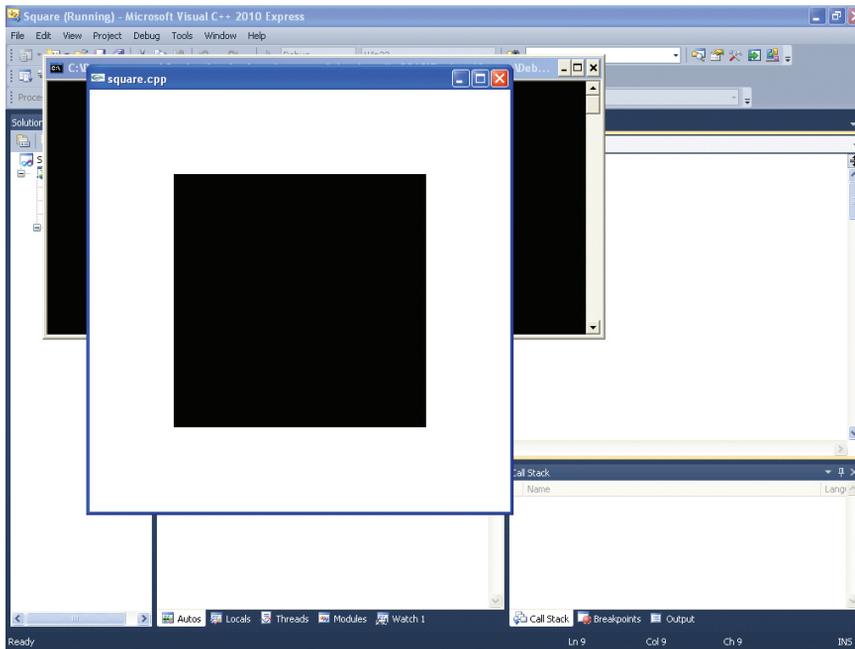


Figure B.9: Square.cpp output in Windows XP.

## B.2 Mac OS X Snow Leopard

The steps to installing and running OpenGL on the Mac OS X are few because OpenGL is integrated into the operating system:

- Install GLEW by going to <http://glew.darwinports.com/> and following instructions there.
- Open a book program or write your own using your preferred editor. Let's assume the program file is `square.cpp`.
- Open the terminal window, change to the directory where the source code is located and compile the program with the command `g++ square.cpp -o square -framework Cocoa -framework OpenGL -framework GLUT`.
- Run the program by entering the command `./square`. Figure B.10 shows the output of our `square.cpp` program.

*Note:* For a GLSL program the command is `g++ glslProgram.cpp -o glslProgram -framework Cocoa -framework OpenGL -framework GLUT -I/opt/local/include -L/opt/local/lib -lGLEW`

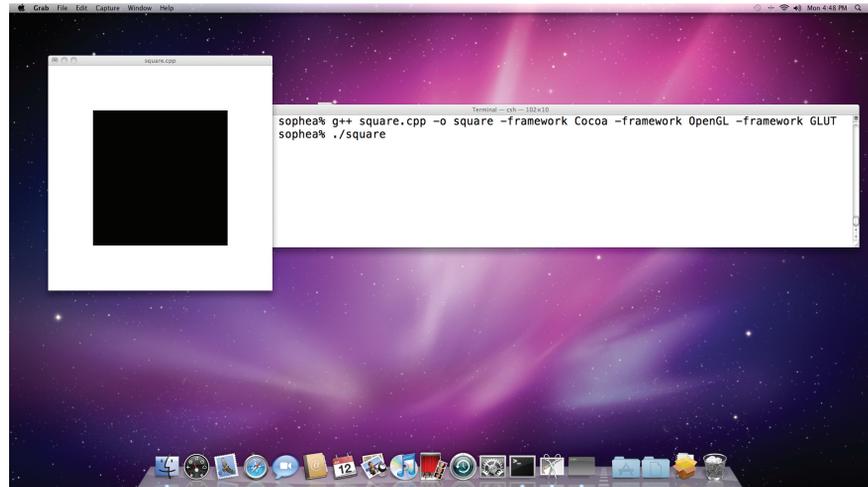


Figure B.10: Square.cpp output in Mac OS X Snow Leopard.

## B.3 Ubuntu Linux

Here are the steps to setting up and running OpenGL on the Ubuntu Linux distribution:

- Go to **System** → **Administration** → **Synaptic Package Manager** and check the boxes to install `g++`, `libglut3-dev` and `libglew-dev`. Synaptic Package Manager will ask you to install dependent packages if necessary for the C++, GLUT and GLEW libraries.
- Open a book program or write your own using your preferred editor. Let's assume the program file is `square.cpp`.
- Open the terminal window, change to the directory where the source code is located and compile the program with the command `gcc square.cpp -o square -I/usr/include -L/usr/lib -lglut -lGL -lGLU -lX11`.
- Run the program by entering the command `./square`. Figure B.11 shows the output of `square.cpp` program.

*Note:* For a GLSL program the command is `gcc glslProgram.cpp -o glslProgram -I/usr/include -L/usr/lib -lglut -lGLEW -lGL -lGLU -lX11`.

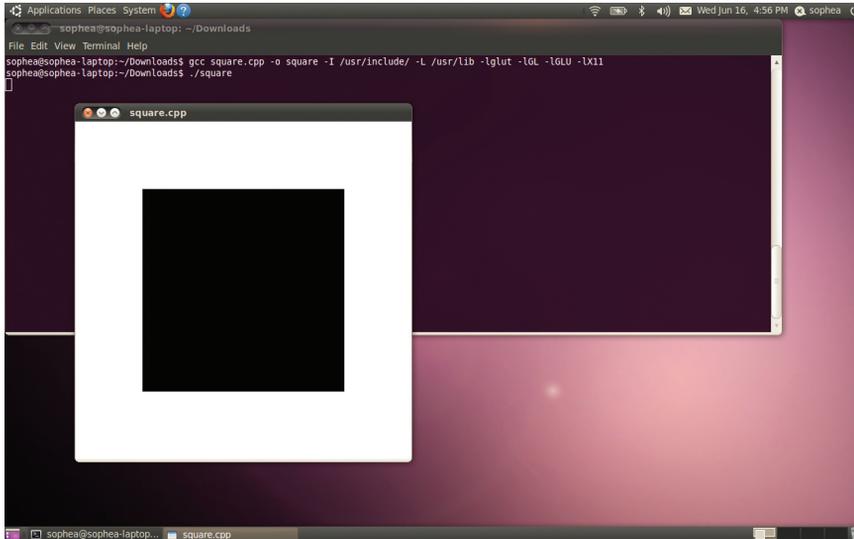


Figure B.11: Square.cpp output in Ubuntu 10.04.